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#### Simulation of a Micro-Scale Out-of-plane Compliant Mechanism

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## Introduction

In this work we present the simulation of a micro-scale large displacement compliant mechanism called the Tsang suspension. It consist of a flat micro-plate anchored down by two springs on either side, that can rotate out-of-plane and maintain its vertical assembly by simple single-axis actuation.

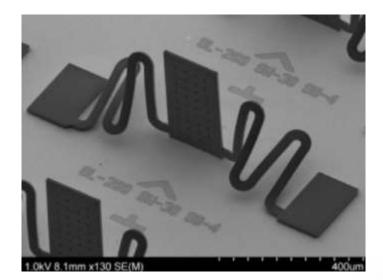


Fig. 1 SEM image of fabricated and assembled SU-8 Tsang Suspension.



# Introduction

Tsang structures can be used in applications such as micro-mirrors [3], free-space optics [4-6] and RF systems [7]. Out-of-plane electro thermal actuators have been fabricated using the Tsang suspension, where an actuator design was connected to the springs instead of the plate [8]. Tsang suspensions have also been used in thermal isolation of sensors [9,10].

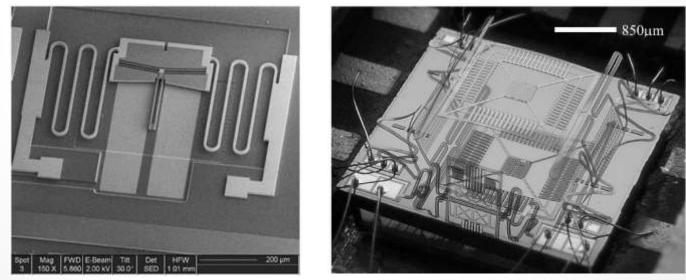
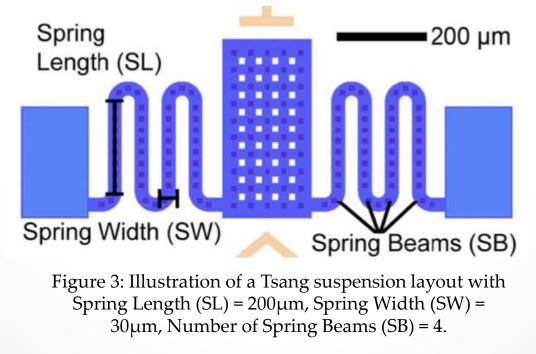


Fig. 2 Left: Electro-thermal micro-gripper for an out-of-plane mirror in Silicon [2]. Right: Several Tsang suspensions (Silicon and Polyimide) hold an elevated platform with a 2 axis thermal accelerometer [3].

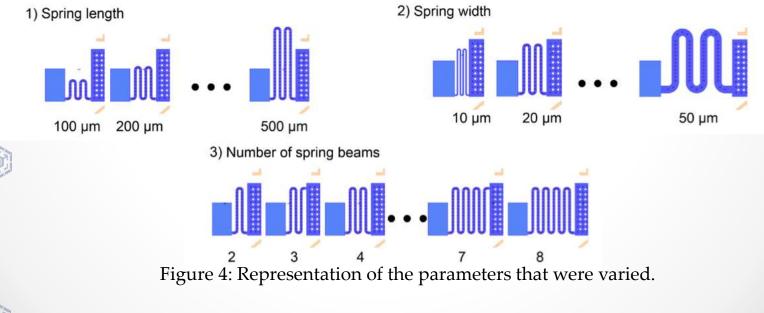
# Simulation Design

The Tsang suspension is composed of symmetric springs, an unanchored platform, and the anchor pads (substrate), as shown in Figure 3. An in-plane force applied to the bottom edge of the central platform produces a complex deformation of the springs, which produces the desired out-of-plane motion of the central platform.





- The design parameters investigated in this work were: the spring length (SL), the spring width (SW), and the number of spring beams (SB).
- The notation {SL, SW, SB} will be used to refer to a specific design. For example, the notation {300, 20, 6} refers to a Tsang suspension with SL = 300  $\mu$ m, SW = 20  $\mu$ m, and SB = 6.



# Simulation Design

In order to facilitate comparisons between various designs, a "standard design" Tsang suspension was established with the parameters SL = 200  $\mu$ m, SW = 30  $\mu$ m, and SB = 4 {200, 30, 4}. This was used as the base point for the various parameter variations investigated. The standard design was chosen since experience with SU-8 fabricated devices, has previously shown it as a reliable and stable design.

Figure 5: COMSOL model of a Tsang {200, 30, 4}

# Use of COMSOL

- One of the challenges of Micro Electromecahnical Systems (MEMS) is the direct measurement of their mechanical properties, due to the fact that the device's dimensions are small, typically <1mm.</li>
- We deal with a large displacement compliant mechanism with torsion.
- Complex to model analytically.
- Common solution is to use nonlinear finite element modeling.

# **COMSOL** Simulation

- The structures were parametrically modeled in COMSOL.
- Material and boundary conditions were selected to represent the assembly process
- The highly nonlinear option was selected to contemplate the large displacements of the structure.

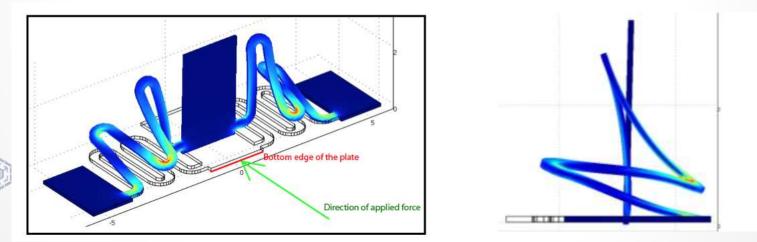


Figure 6: Tsang suspension assembly in COMSOL.



# **Simulation Results**

- Scanning Electron Miscroscopy (SEM) was use to capture the topview of the assembled structures.
- The simulation had good agreement with the experimental assembly.

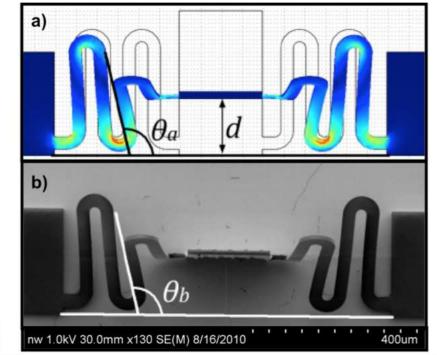
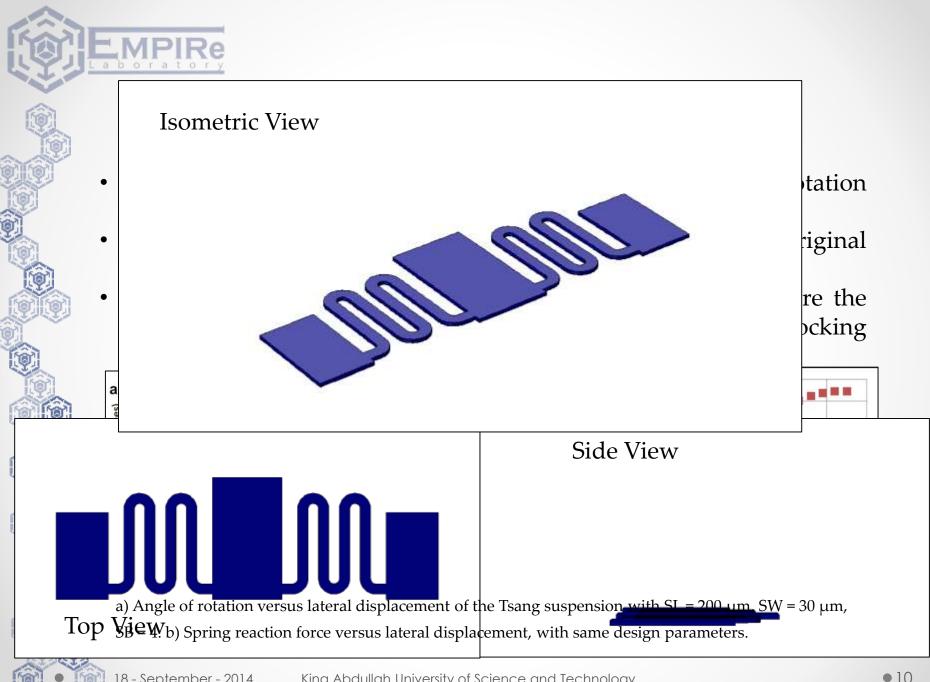


Figure 7: Top view of simulation and SEM image. An example comparison angle, "theta-a" and "theta-b". And displacement to vertical "d" are shown.

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### **Simulation Results**

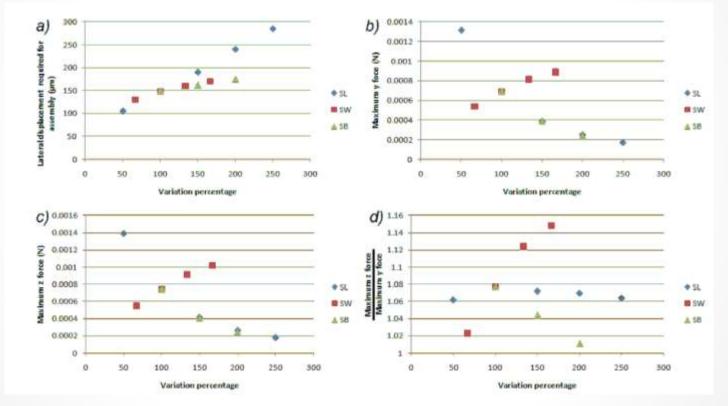


Figure 8: Graphs showing the effect of varying the different parameters as percentage variation of the standard design {200,30,4}

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## Conclusions

- The Tsang suspension and its design parameters were studied using COMSOL Multiphysics.
- Changes in the reaction forces and displacement required for assembly were determined.
- Clear trends are observed when varying design parameters.
  - This work provides greater insight into the operation of Tsang suspensions and provides designers with tools for designing their own implementation.

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## Thank You!

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