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Estimation Of Boundary Properties Using Stochastic Differential Equations

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Outline



Motivation

- Inverse Problems in Diffusion
- Problem Description
- Physical Model
 - Stochastic Differential Equation (SDE)

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- Fokker Planck Equation
- 4 Statistical Model
 - Modeling the Total Absorption
 - Modeling the Sector Absorption
 - Estimation Algorithm



Numerical Examples

Inverse Problems in Diffusion

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Inverse Problems in Diffusion

- It has many applications in thermal, biomedical, financial ... etc.
- Estimation of medium properties (diffusivity).
- Estimation of source properties (location, intensity, and release time).
- Estimation of boundary properties.

Problem description

- Circular region with radius *R* centered at origin.
- Boundary is divided into two segments:
 - Absorbing with a length of *I* and centered at α .
 - The rest of the boundary is reflecting.
- The main goal here is to estimate the parameters of the absorbing boundary (i.e. *I* and α).



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Stochastic Differential Equation (SDE) Fokker Planck Equation

Stochastic vs Classical Approach

Let us assume

- When the number of particles is large, macroscopic approach corresponding to the Fick's law of diffusion is adequate.
- When their number is small, a microscopic approach corresponding to SDE is required.







Stochastic Differential Equation (SDE) Fokker Planck Equation

Stochastic Differential Equation (SDE)

The SDE process for the transport of particle is given by

$$\mathrm{d}X_t = \mu(X_t, t)\mathrm{d}t + \sigma(X_t, t)\mathrm{d}W_t$$

Boundary conditions

- Absorbing: the displacement remains constant $(dX_t = 0)$.
- Reflecting: the new displacement over a small time step τ is:

$$\mathrm{d}X_t = \mathrm{d}X_{t1} + |\mathrm{d}X_{t2}| \cdot \hat{r_R} \quad (2)$$





(1)

Stochastic Differential Equation (SDE) Fokker Planck Equation

Fokker Planck Equation

The probability density function of one particle occupying space around r at time t is given by the solution of

$$\frac{\partial f(\boldsymbol{r},t)}{\partial t} = \left[-\sum_{i=1}^{3} \frac{\partial}{\partial x_{i}} D_{i}^{1}(\boldsymbol{r}) + \sum_{i=1}^{3} \sum_{j=1}^{3} \frac{\partial^{2}}{\partial x_{i} \partial x_{j}} D_{ij}^{2}(\boldsymbol{r}) \right] f(\boldsymbol{r},t) \quad (3)$$

Along with the initial condition at $t = t_0$ is given by

$$f(\boldsymbol{r}, t_0) = \delta(\boldsymbol{r} - \boldsymbol{r}_0) \tag{4}$$

(5)

And the boundary conditions

 $f(\mathbf{r}, t) = 0$ for absorbing boundaries

 $\frac{\partial f(\mathbf{r}, t)}{\partial n} = 0 \quad \text{for reflecting boundaries} \quad (6)$

Stochastic Differential Equation (SDE) Fokker Planck Equation

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Fokker Planck Equation



Modeling the Total Absorption Modeling the Sector Absorption Estimation Algorithm

Modeling the Total Absorption

Modeling procedure

- Simulating initial number of particles ($n_0 = 1000$).
- The simulation is repeated 5000 times.
- The average percentage number of absorbed particles (n_{absorbed}/n₀) is plotted as a function of t and l.



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Modeling the Total Absorption Modeling the Sector Absorption Estimation Algorithm

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Modeling the Total Absorption

Result

The relation between the percentage number of absorbed particles, time and *I* is given by

$$n_{absorbed}/n_0 = (2/\pi) \arctan(a(l)t^3 + b(l)t^2 + c(l)t + d(l))$$
 (7)

where *a*, *b*, *c*, and *d* are functions of *l* and can be fitted using cubic polynomials in order to have a smooth behavior with respect to *l*.

Modeling the Total Absorption Modeling the Sector Absorption Estimation Algorithm

Modeling the Total Absorption

Modeling procedure

- Circular geometry is divided into S sectors.
- Simulating initial number of particles ($n_0 = 1000$).
- The simulation is repeated 5000 times.
- The average number of particles in each sector is plotted as a function the rogation angle ϕ and time.



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Modeling the Total Absorption Modeling the Sector Absorption Estimation Algorithm

Modeling the Total Absorption

Result

The average number of particles per sector shows a local minimum near α . The relation between α and the minimum of n/n_0 can be represented as follows

$$\alpha = \arg\min_{\phi} n/n_0 \tag{8}$$

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Modeling the Total Absorption Modeling the Sector Absorption Estimation Algorithm

Estimation Algorithm

Step1

Let y_{t_j} to be the measured number of particles at time t_j , where j = 1, ..., k and k is the total number of time samples. Then, the corresponding segment length l_j can be estimated by

$$I_j = \arg\min_{l} |y_{t_j} - g(l, t_j)|$$
(9)

(10)

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The estimated segment length is taken to be

$$\bar{l} = \frac{1}{k} \sum_{j=1}^{k} l_j$$

Modeling the Total Absorption Modeling the Sector Absorption Estimation Algorithm

Estimation Algorithm

Step2

Let y_{i,t_j} to be the measured number of particles at sector *i* and time $t = t_j$ where i = 1, ..., S and *S* is the total number of sectors. The corresponding boundary center (α_j) can be estimated for each time step by

$$\alpha_j = \alpha(\arg\min_i y_{i,t_j}) \tag{11}$$

(12)

The estimated α is taken to be

$$\bar{\alpha} = \frac{1}{k} \sum_{j=1}^{k} \alpha_j$$

Numerical Examples

Parameters

- Source strength of $n_0 = 500$ particles.
- Initially at $\mathbf{r}_0 = 0$ and $t_0 = 0$.
- Bounded by a circular domain of radius R = 1.
- The number of time samples is k = 30.
- The results are carried out for absorbing regions of (*l* = π/3, π/6, π) a centered at α = π/2.

Numerical Examples

Results				
absorbing length	$\pi/3$	$\pi/6$	π	
% error in /	1.23e-2	1.04e-2	1.34e-2	
% error in α	4.2e-2	3.91e-2	4.02e-2	

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- In this paper we propose a preliminary algorithm for the estimation of the boundary properties
- The accuracy of this method is reasonable compared to the computational effort required for the estimation
- This algorithm can be used in applications where the estimation time has higher priority with acceptable margin of error

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Thank You!

