

# **On The Simulation of Electromagnetic Forming Process of Tube Using Multiphysics Software**

**Presented by**

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# Outline of Paper

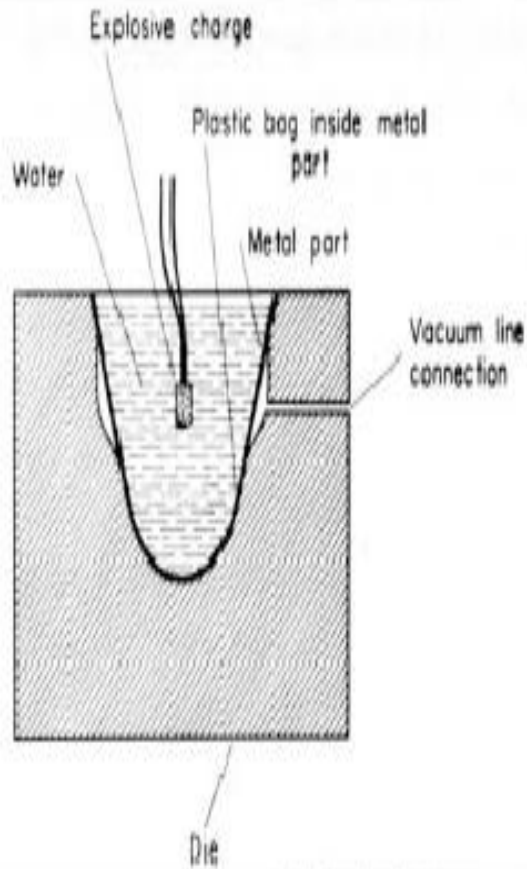
- Aim of paper.
- High Velocity Forming(HVF).
- Electromagnetic forming(EMF).
- Simulation.
- Results and Conclusion.

# Aim of Paper

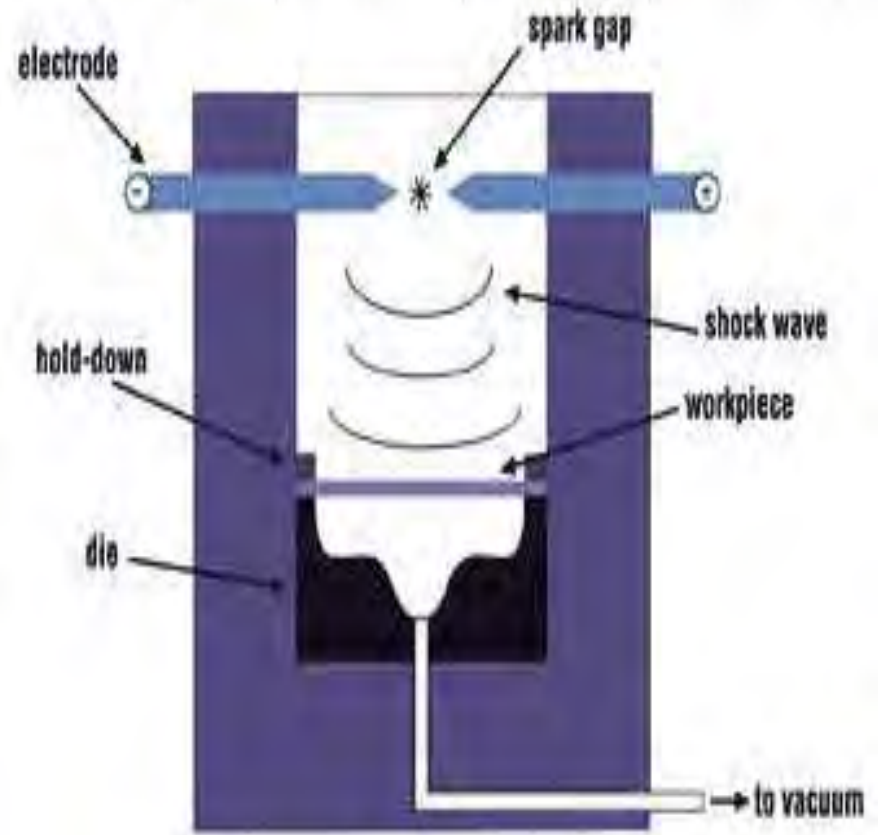
- Demonstrating that Electromagnetic process can be simulated with a relatively simple model that has good correspondence to experimental data.
- Also, the validated model should be able to predict deformation at energy levels that cannot be achieved within safe operating limits of the equipment used presently, but can serve as a guide for next generation equipment.

# What Is High Velocity Forming

- **High velocity forming (HVF)** is the shaping of materials by rapidly conveying energy to them during short time durations.
- It is also known as a **HERF/HVF** process.
- The HVF forming velocity of workpiece reaches up to 100m/sec in less than 0.1 ms .
- The HERF processes are:
  - (i) Explosive, (ii) Electro-Hydraulic, and
  - (iii) Electromagnetic Forming.
- EMF is the most widely used HERF process in industries

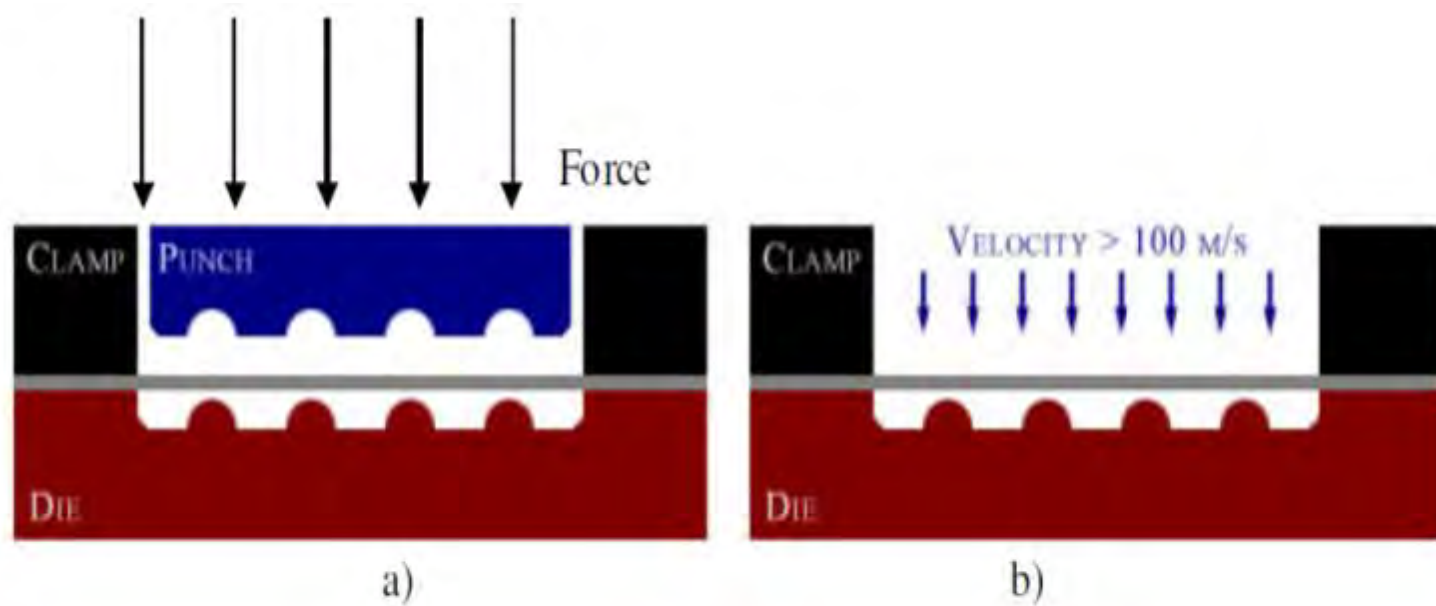


Explosive[1]

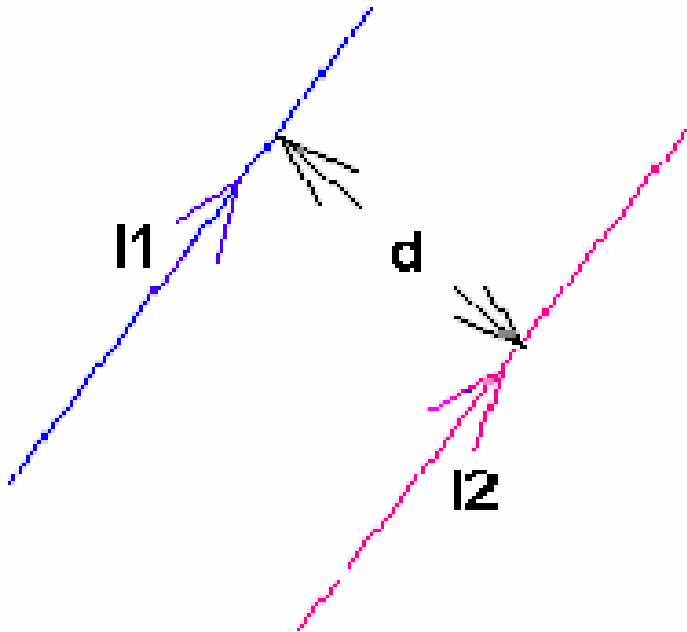


Electro-Hydraulic[1]

# Traditional & Electromagnetic Forming[1]



# Principle of EM Forming



$$F = \frac{\mu_0}{2\pi d} I_1 I_2$$

$F$  = Force; N/m,

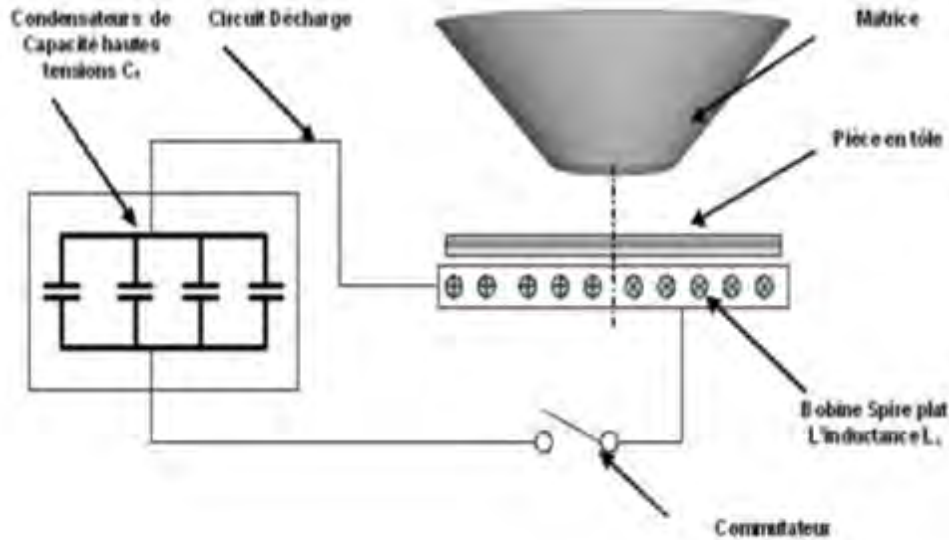
$I_1, I_2$  = Current; A

$d$  = Spacing between conductors

$\mu_0$  = permeability of free space;

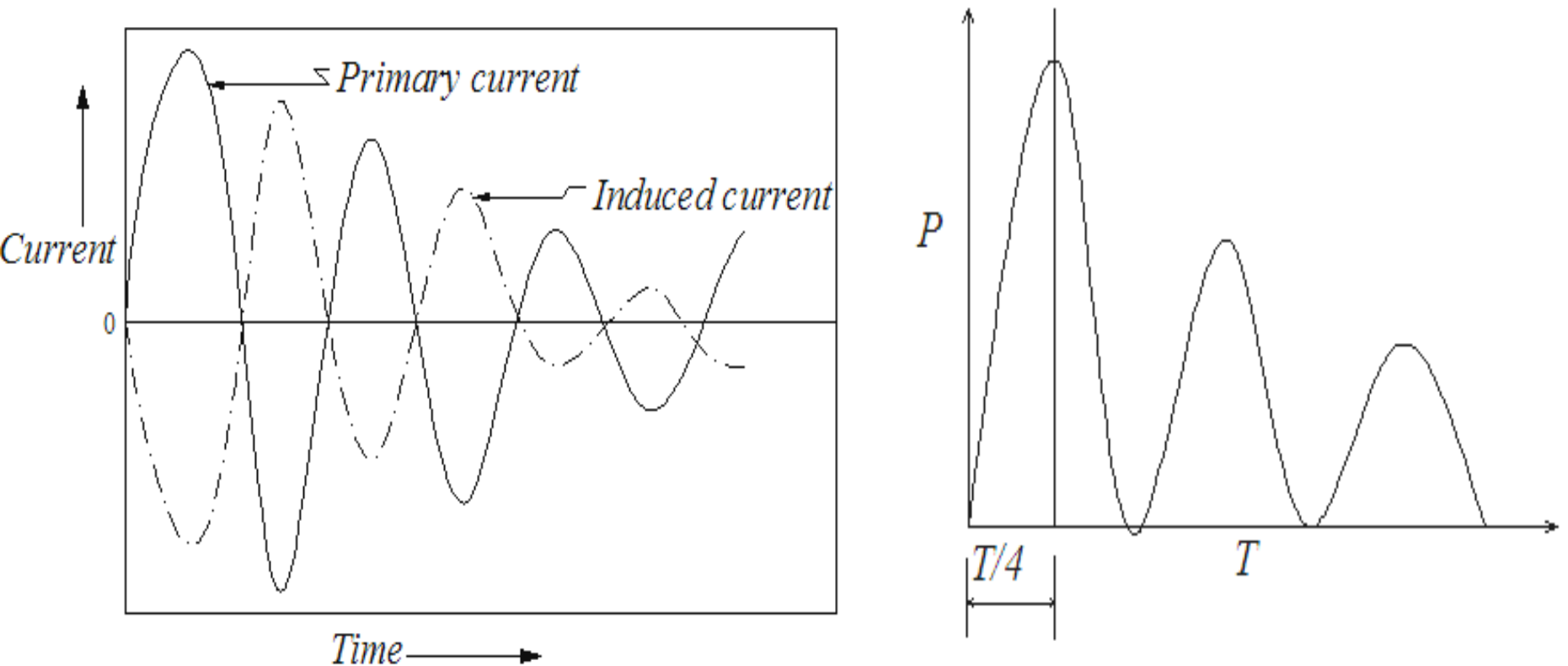
H/m

# Electromagnetic Forming





# Current and pressure in EMF Process



$$I(t) = \frac{V_0}{\omega L} e^{\frac{-R_S t}{2L}} \sin(\omega t)$$

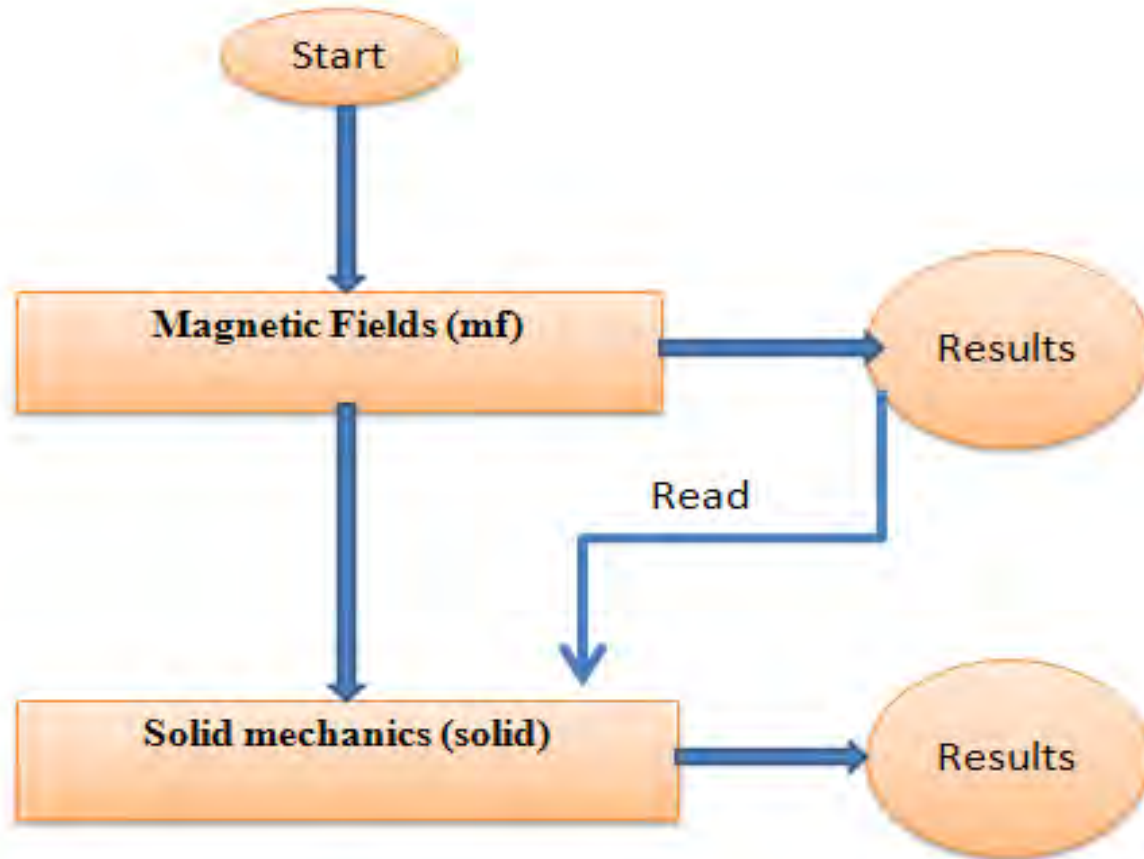
# Application



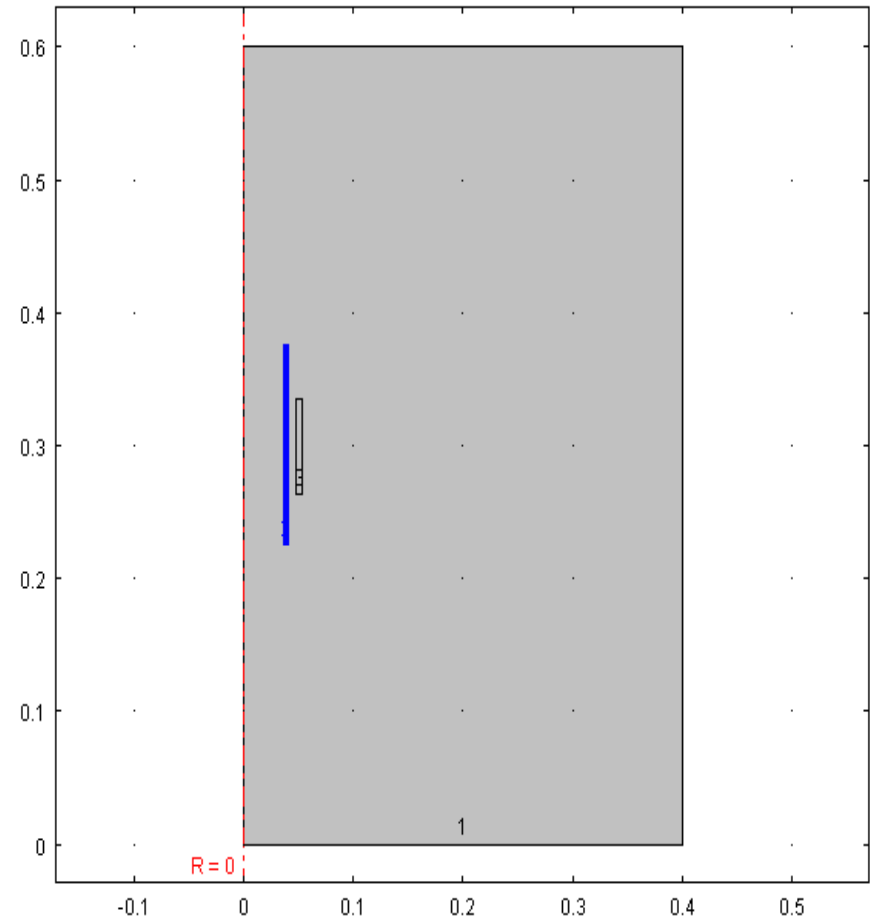
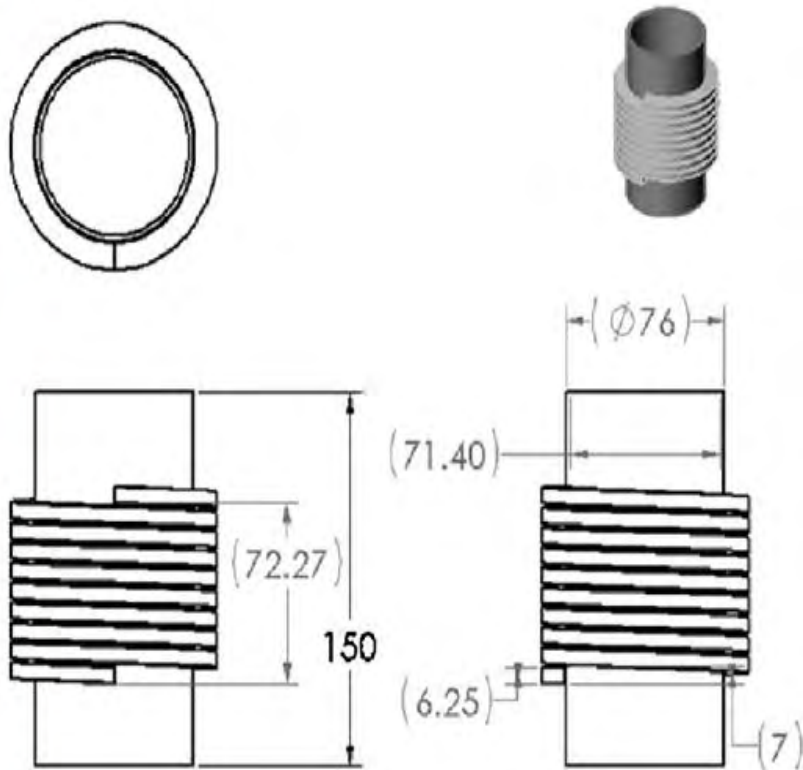
# Application



# Simulation Flow Chart



# Modeling of EMF system



# Global Parameters and Variables.

$$I(t) = \frac{V_0}{\omega L} e^{\frac{-R_s t}{2L}} \sin(\omega t)$$

Settings Material Browser

## Parameters

Parameters

Name	Expression	Value
a	8612.68 [V]	8613 V
b	100e-9 [H]	1.0E-7 H
c	10 [ohm]	10 Ω
d	6677.79 [rad/s]	6678 rad/s
q	.005 [m]	0.005 m
g	.07227 [m]	0.07227 m

Settings Material Browser

## a= Variables

Variables

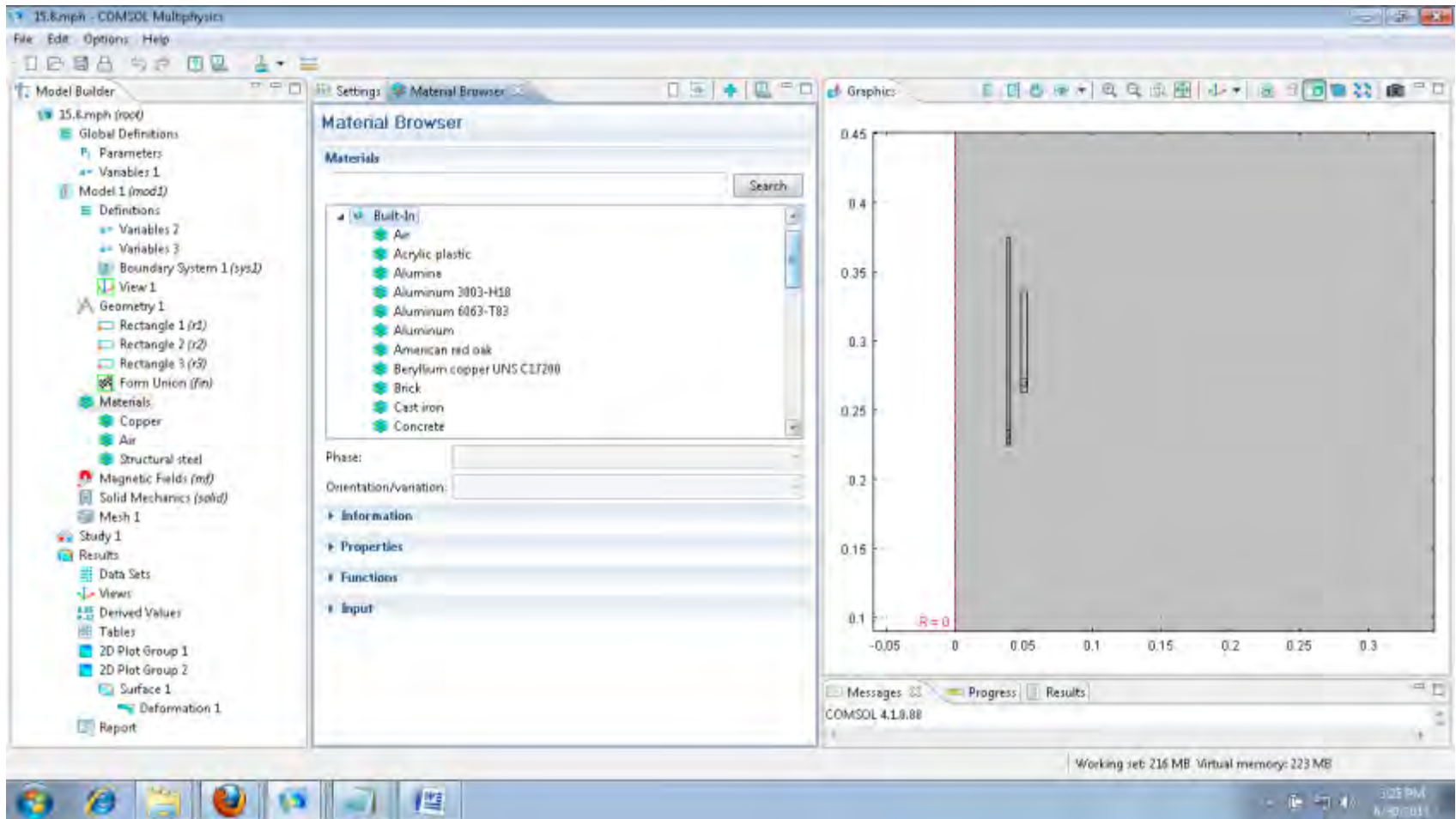
Name	Expression	Unit
I	<code>(a/(d*b))*(e...)*sin(d*t)</code>	A

↑ ↓ ✕ 📄 📁

Name:  
I

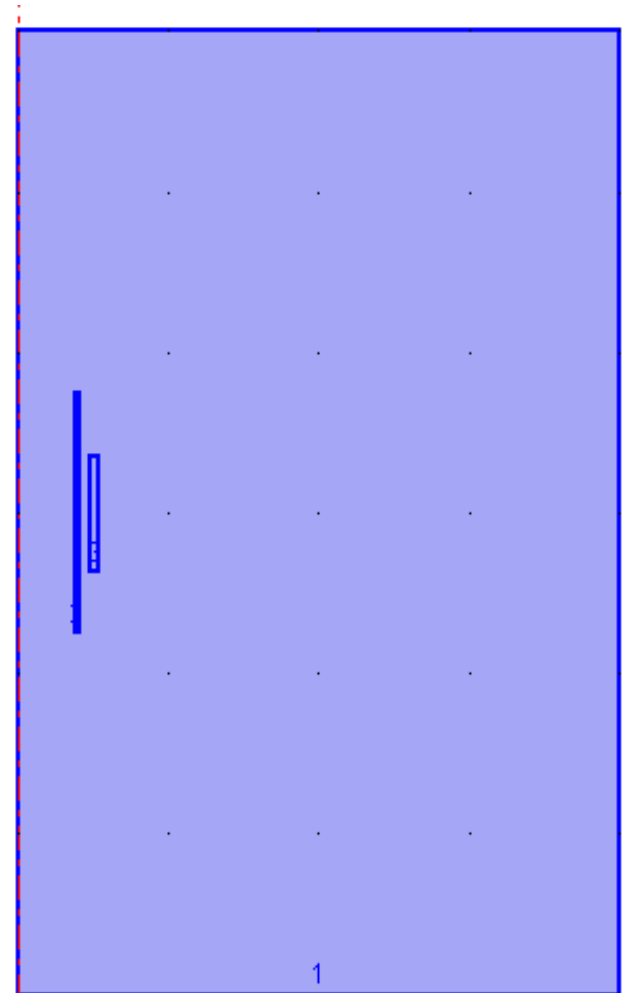
Expression:  
`(a/(d*b))*(exp((-c*t)/(2*b)))*sin(d*t)`

# Define Material

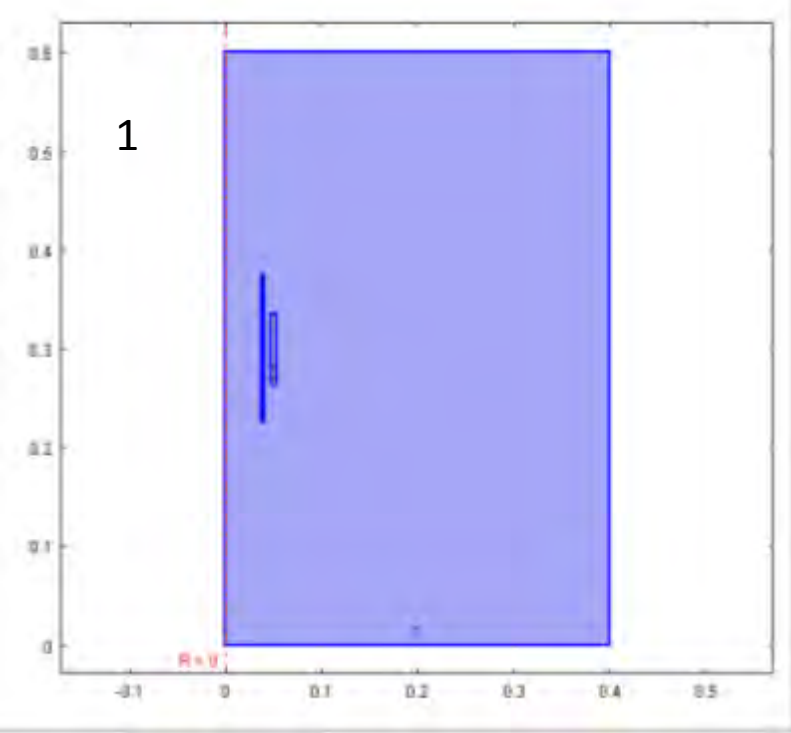


# Magnetic Field Boundary Condition

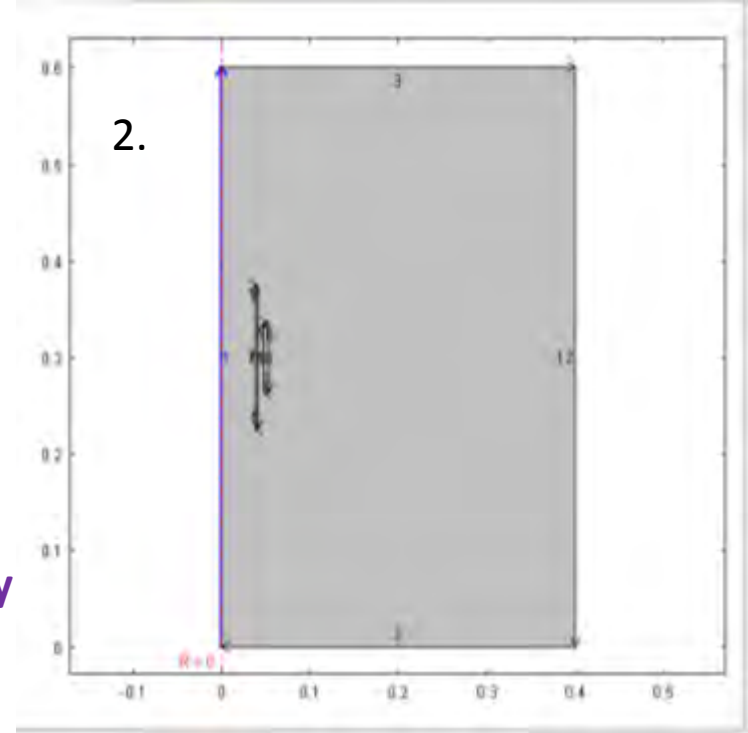
Magnetic field physics is  
applied to all domain



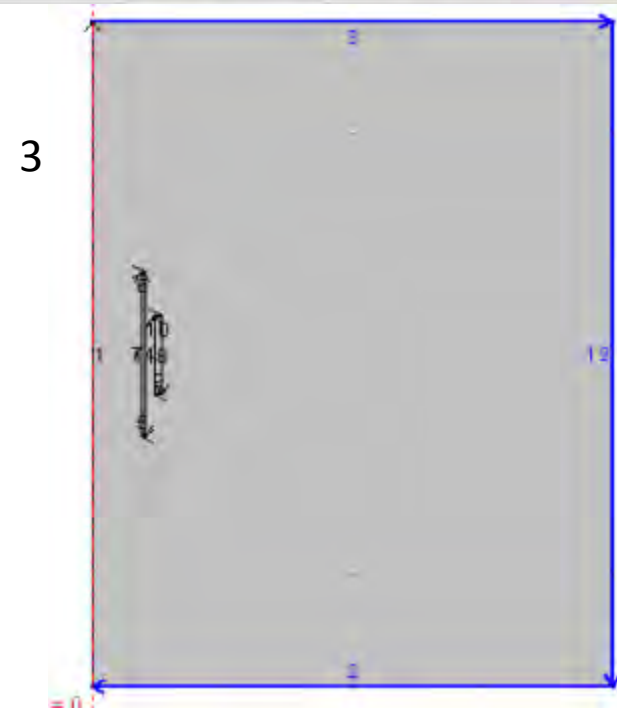




1.Ampere's Law



2.Axial Symmetry



3.Magnetic Insulation

4



4.Initial value

1[atm] Pa

▼ Coordinate System Selection

Coordinate system:  
Global coordinate system

▼ Multi-Turn Coil Domain

Coil name:  
1

Relative permeability:  
 $\mu_r$  From material

Relative permittivity:  
 $\epsilon_r$  From material

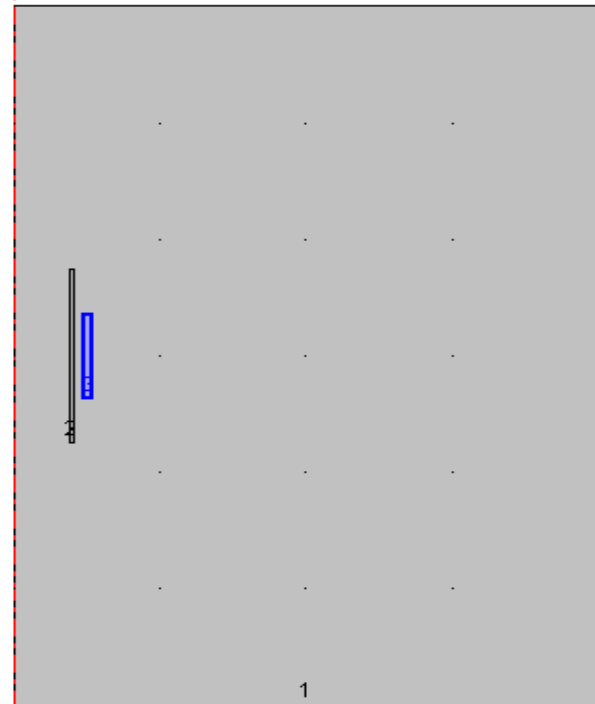
Coil conductivity:  
 $\sigma_{\text{coil}}$  6e7[S/m] S/m

Number of turns:  
 $N$  3

Coil wire cross-section area:  
 $A_{\text{coil}}$  .007\*.00625 m<sup>2</sup>

Coil excitation:  
Current

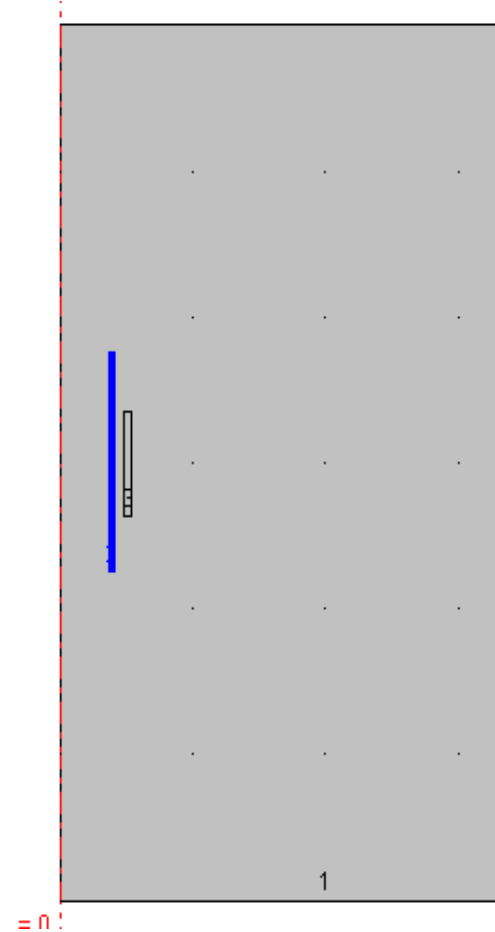
Coil current:  
 $I_{\text{coil}}$  1/(.007\*.00725) A



## 5.Multi-Turn Coil Domain

# Solid Mechanics Boundary Condition

Solid Mechanics is applied to domain 2



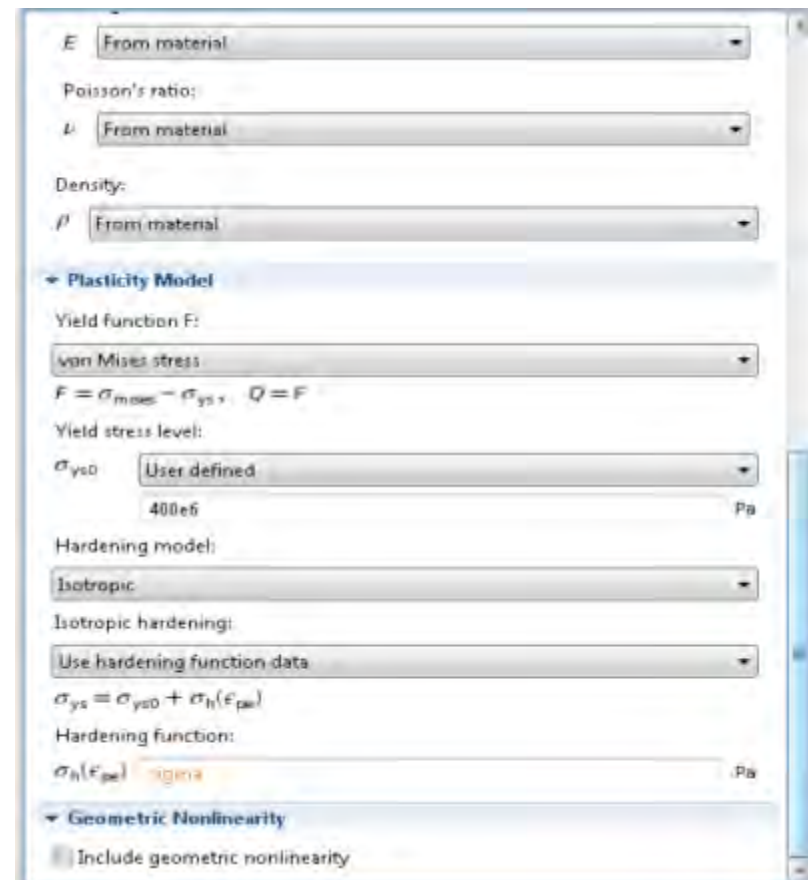
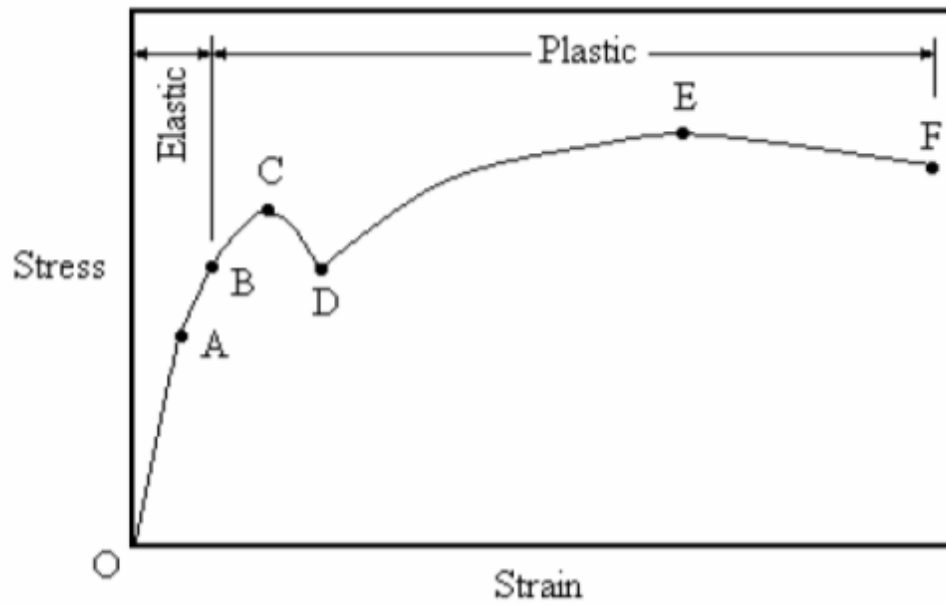


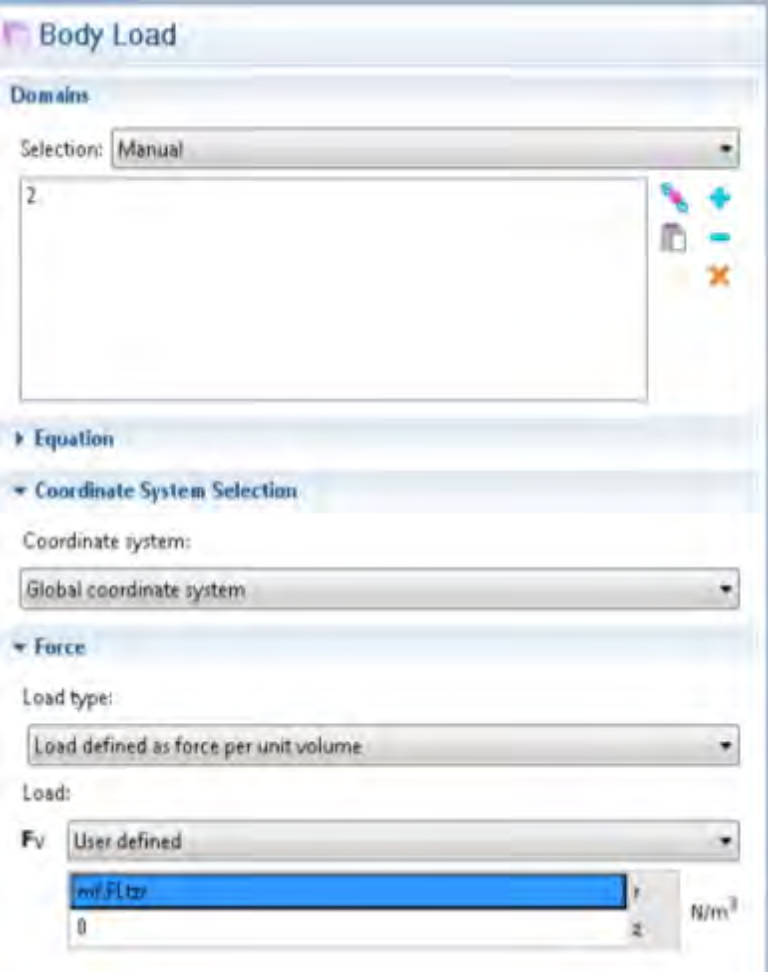
## 1. Initial Values

$$\sigma_{\text{hard}} = \sigma_y \left[ 1 + \left( \frac{\dot{\epsilon}}{P} \right)^m \right] - \sigma_{\text{yield}}$$



## 2. Elastoplastic Material



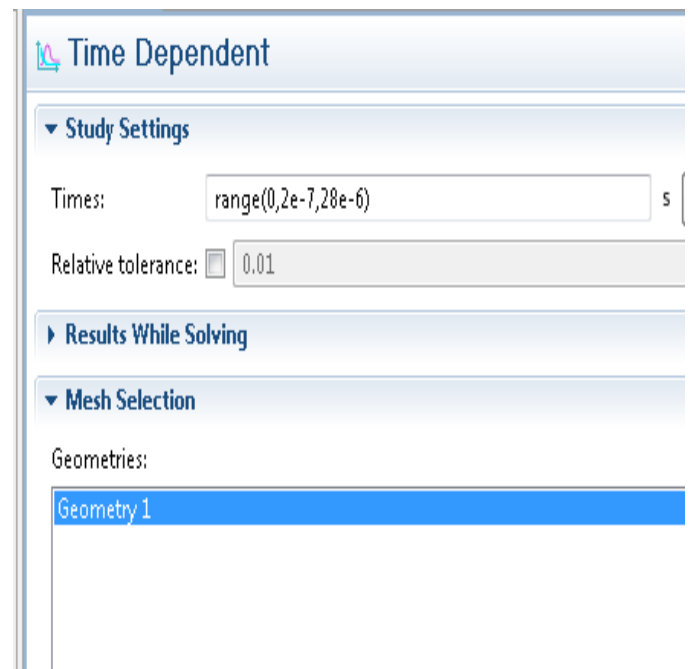


3.Coupling Body Load

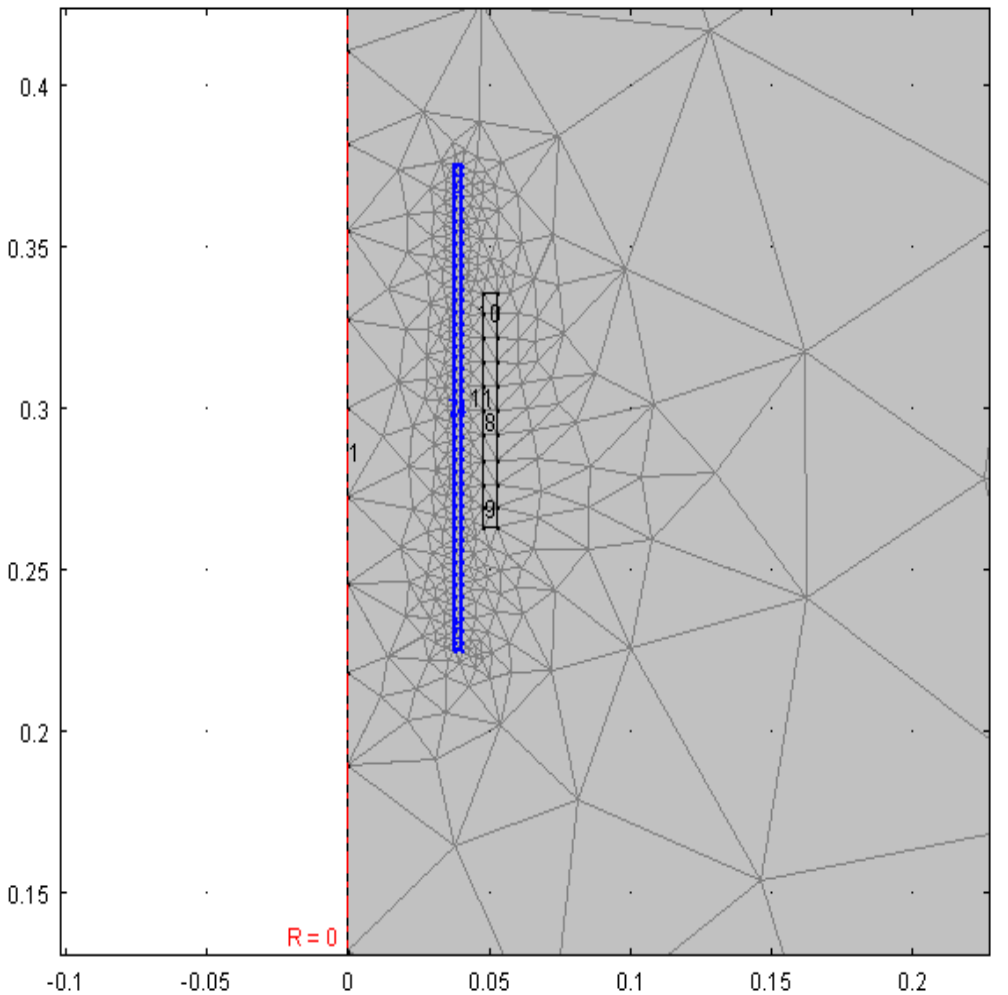
## 4.Prescribed Displacement



## 5.Study- Time Dependant



# Meshing



**Size**

**Element Size**

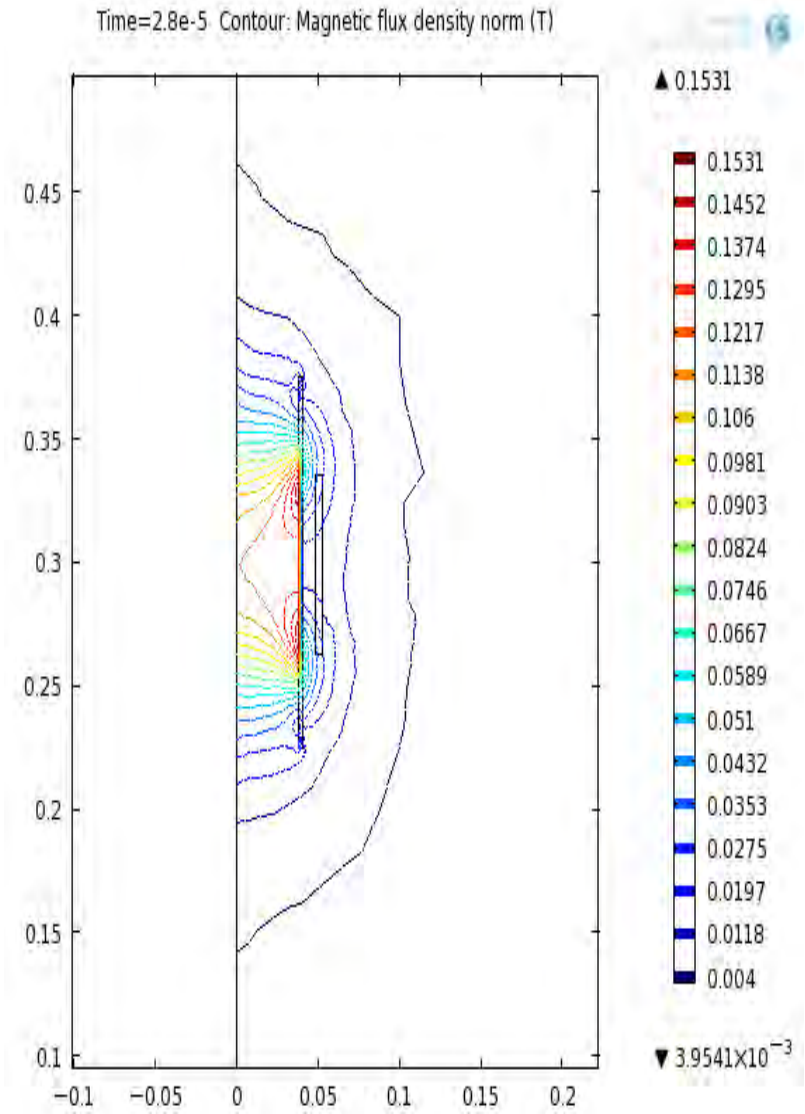
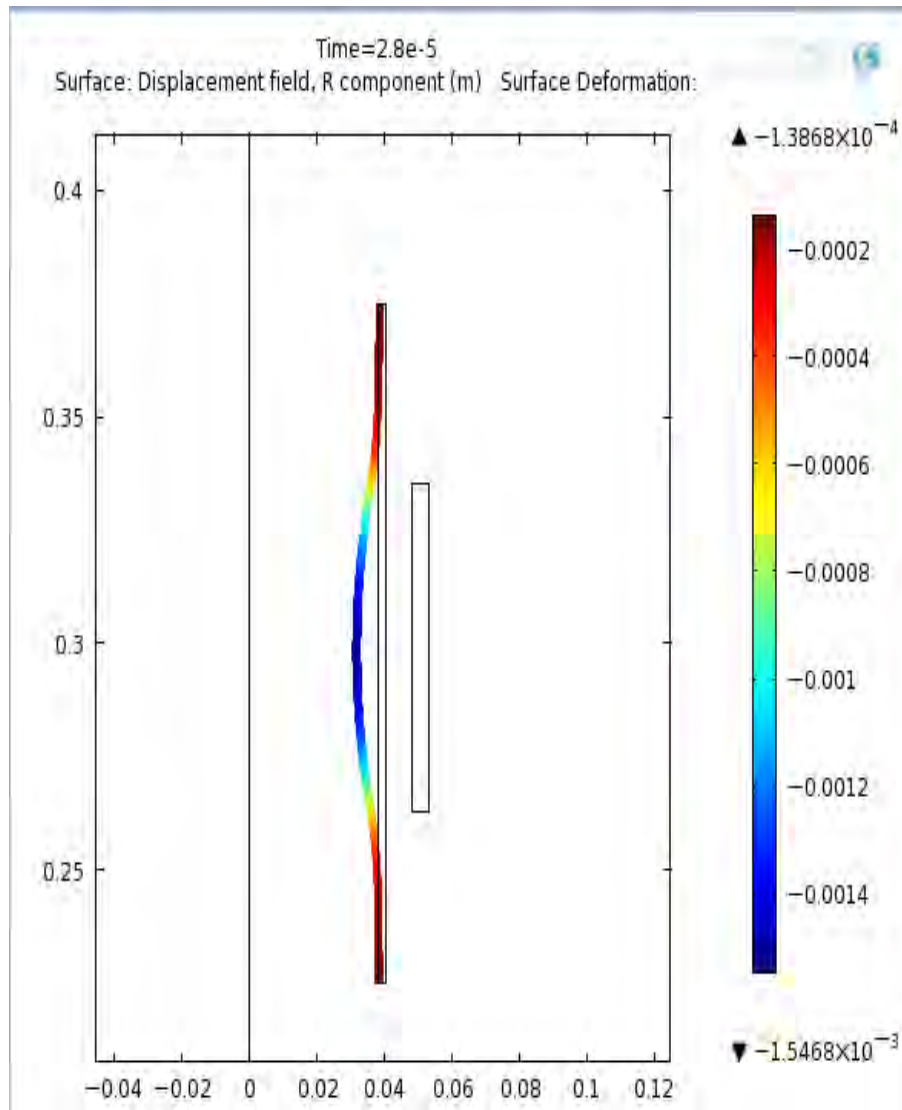
Calibrate for:  
General physics

Predefined  
 Custom

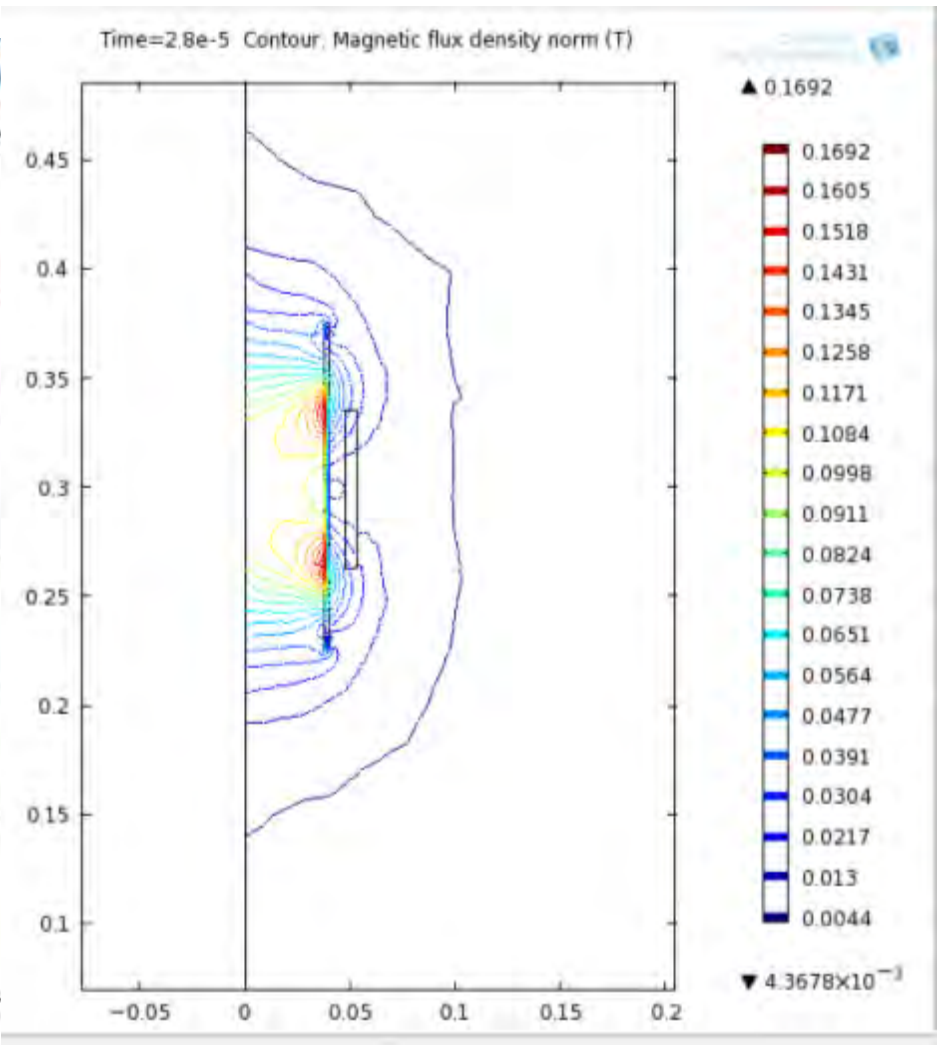
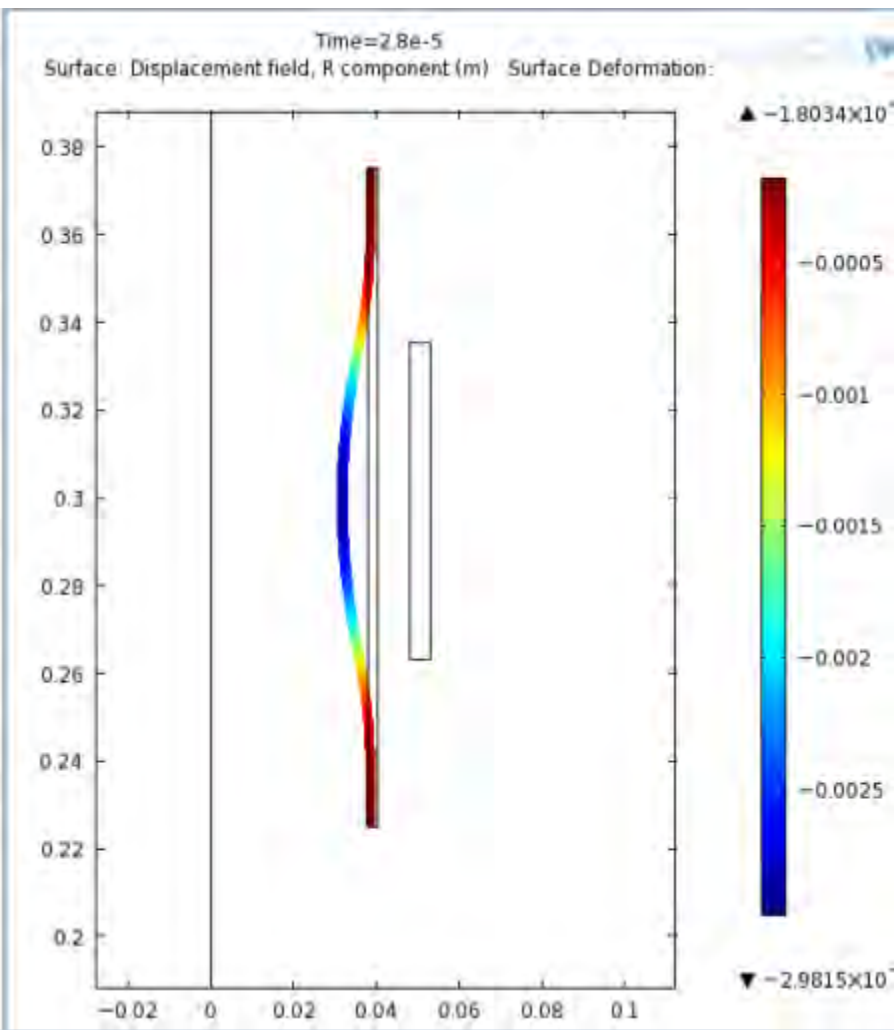
**Element Size**

- Extremely coarse
- Extremely fine
- Extra fine
- Finer
- Fine
- Normal
- Coarse
- Coarser
- Extra coarse
- Extremely coarse

# Displacement and Magnetic Flux Density for 8kJ

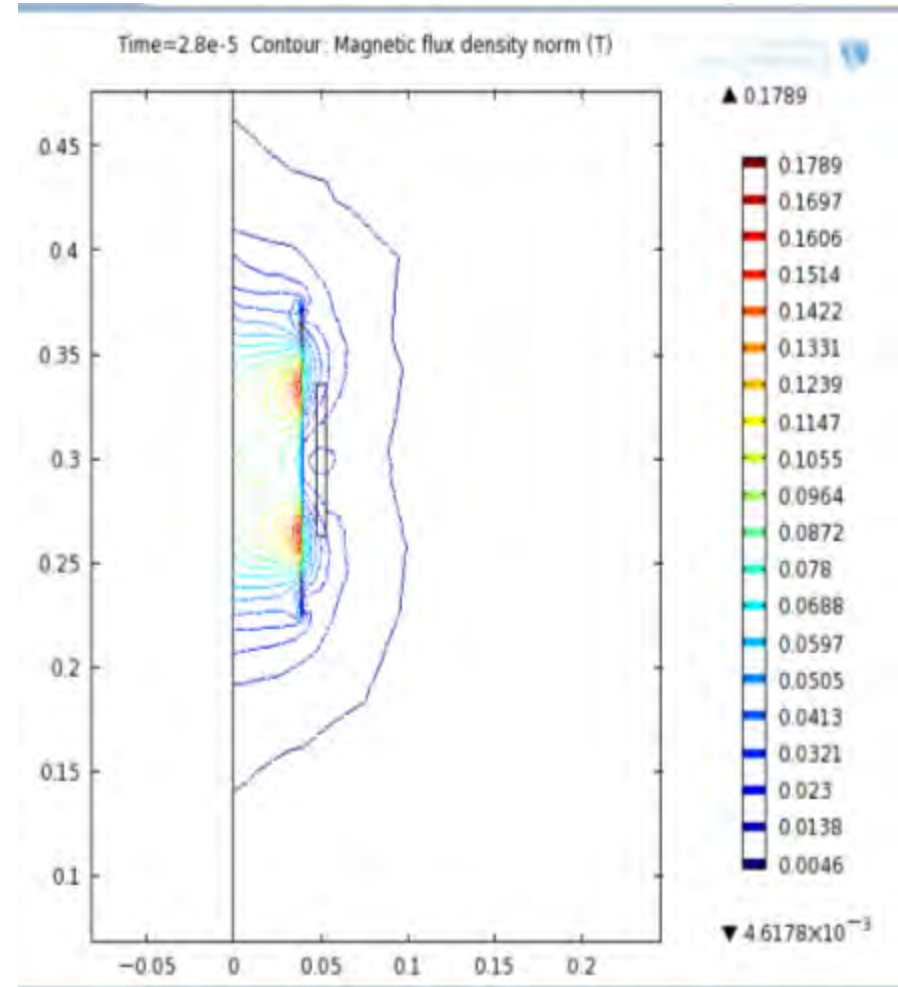
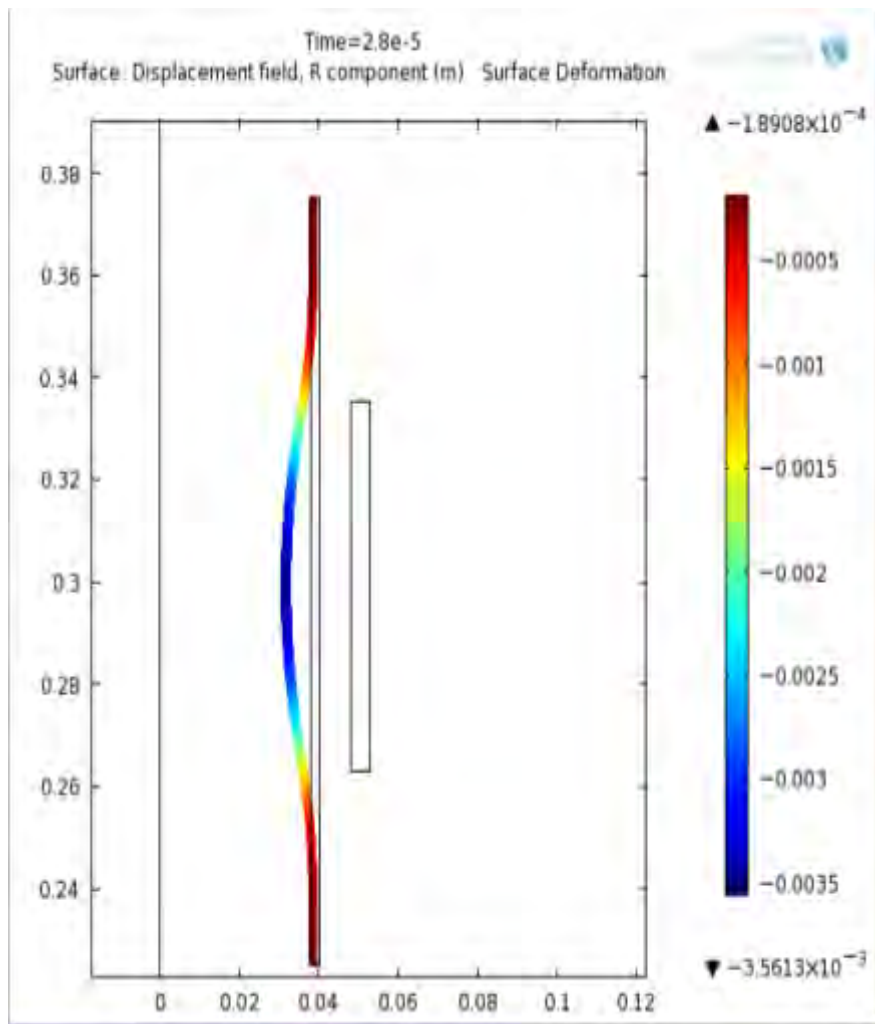


# Displacement and Magnetic Flux Density for 15.8 kJ

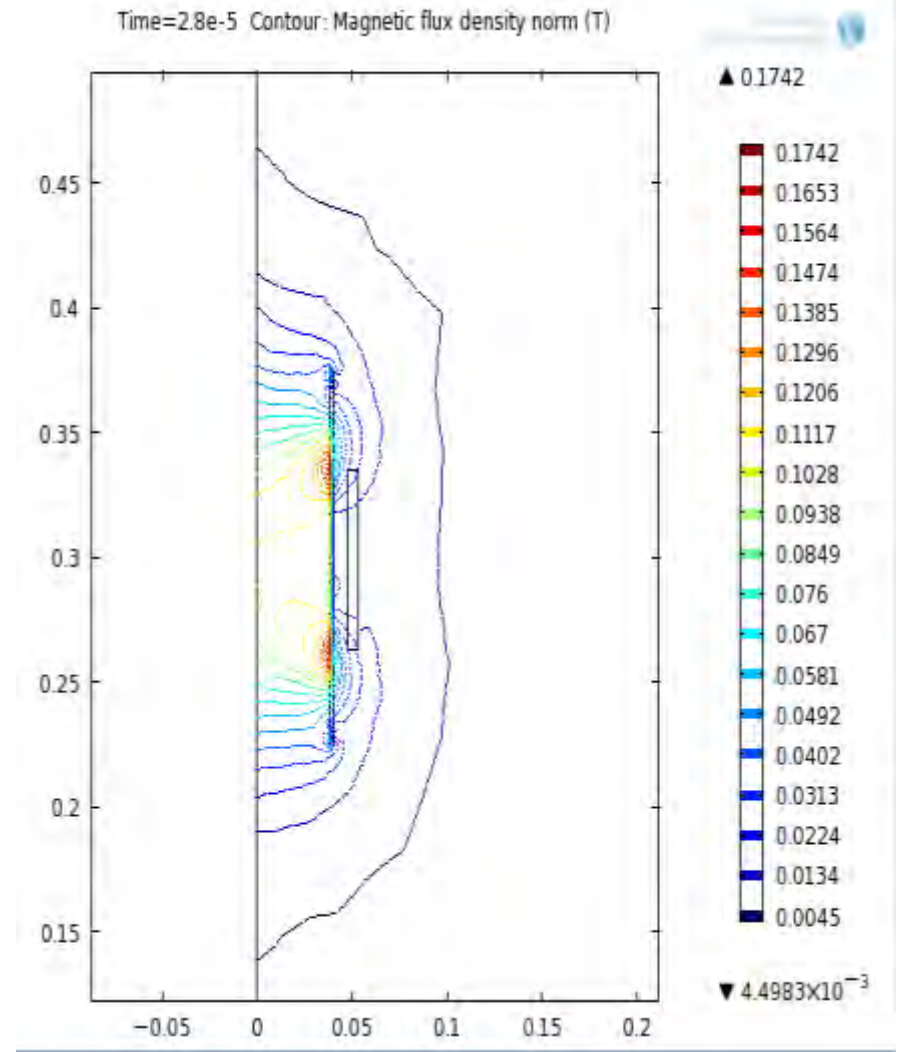
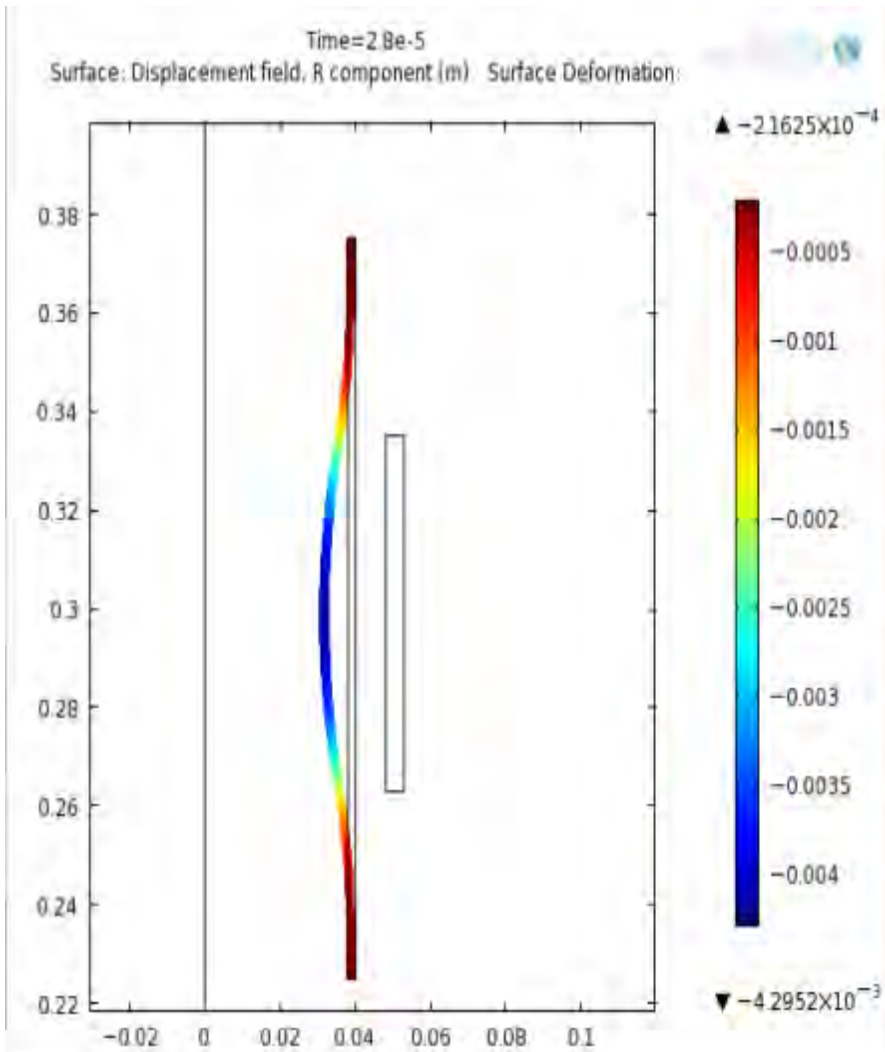




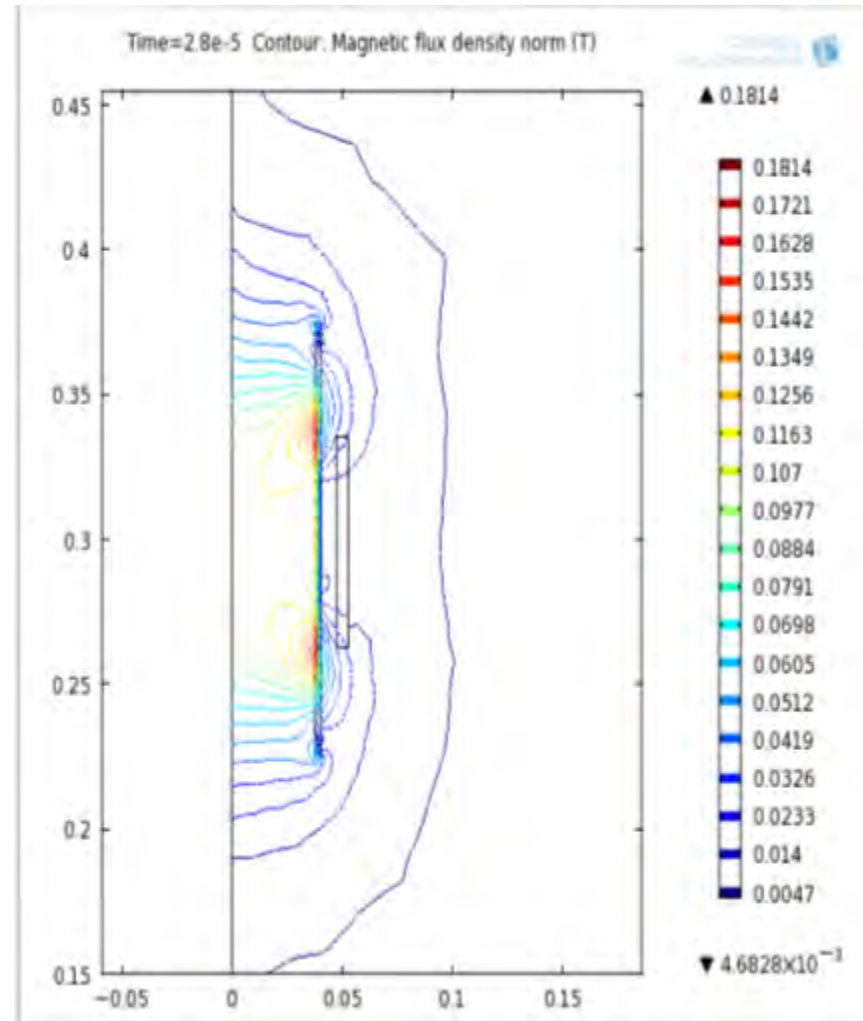
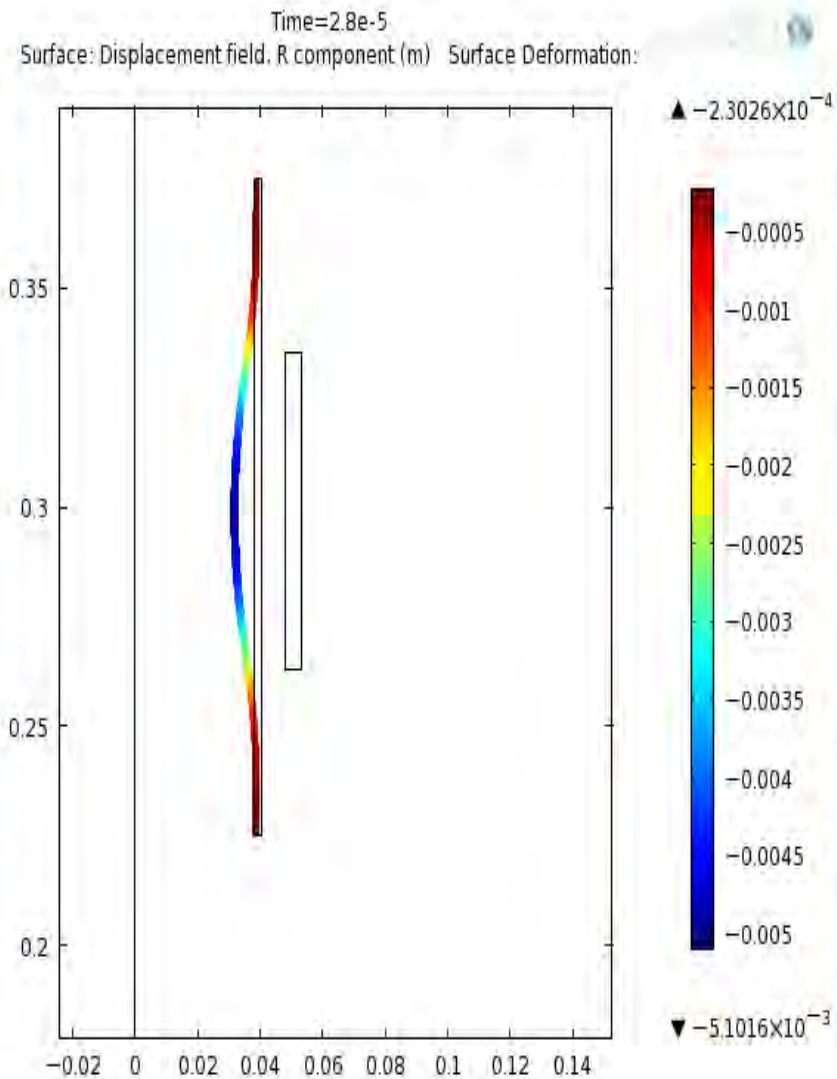
# Displacement and Magnetic Flux Density for 18 kJ



# Displacement and Magnetic Flux Density for 21 kJ



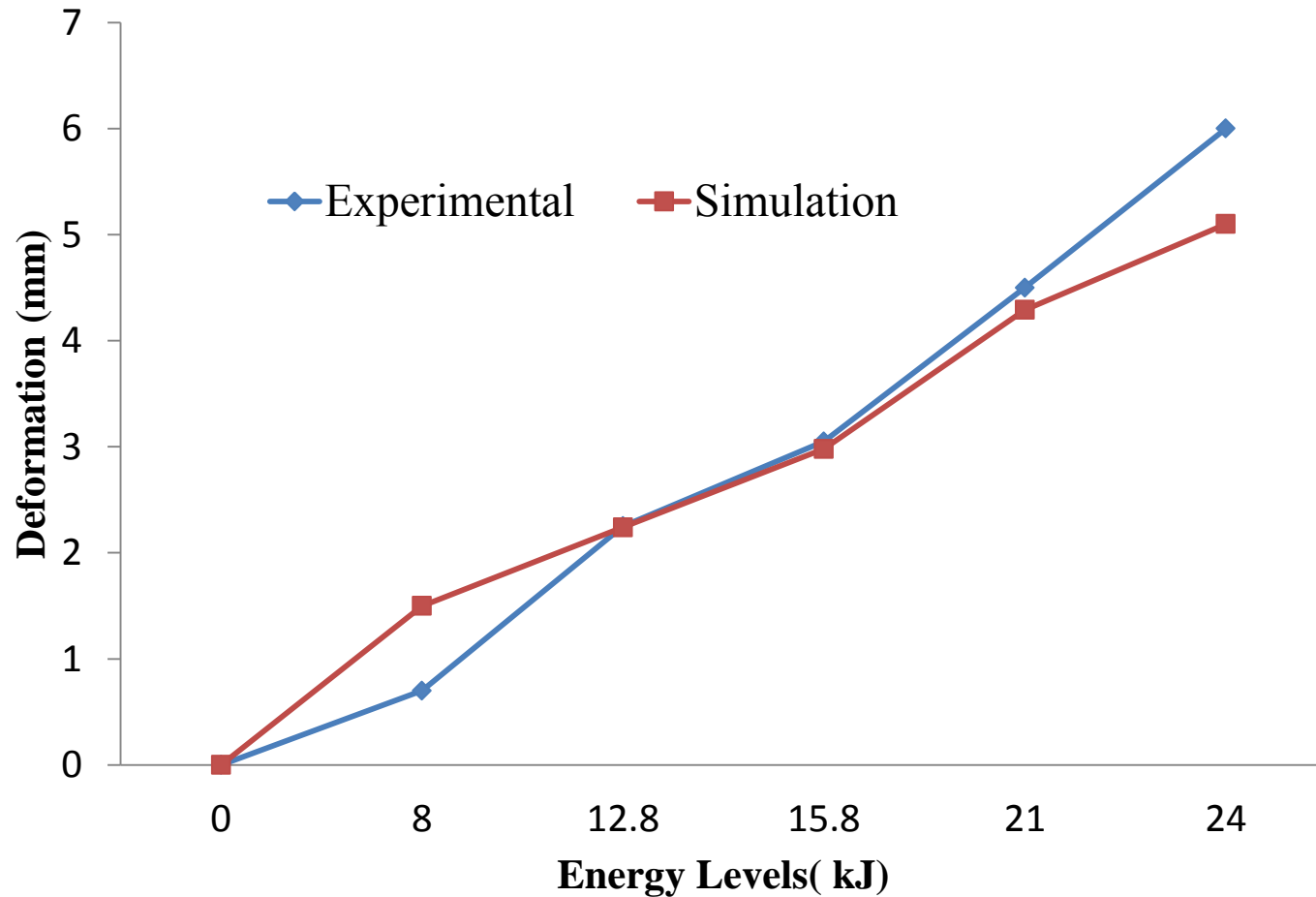
# Displacement and Magnetic Flux Density for 24 kJ



# Results

Energy (KJ)	Rise time ( $\mu$ S)	Final deformation Expt.(mm)	Final deformation simulation (mm)	% reduction	Predicted % reduction
8	28	0.7	1.5	1.8	3.4
12.8	28	2.25	2.24	5.9	5.87
15.8	28	3.05	2.98	8.0	7.9
18	28	3.15	3.5	8.1	9.1
21	28	4.5	4.29	11.8	11.25
24	28	6	5.1	15.9	13.4

# Graph of Deformation (mm) against Energy Levels (kJ)



# Conclusion.

- Simulations were carried out on the electromagnetic compression of high strength (440MPa tensile strength) 76.2mm diameter, 2.3mm wall thickness tubes.
- Significant final deformations over a length of about 75mm were obtained with a fixed 9-turn helical compression coil.
- About 8% and 15% reductions in diameter were developed with 16 kJ and 24 kJ discharges from separate commercial capacitor banks.
- Comparisons between simulations and experimental data from literature gave confidence that a simple numerical model can reliably predict system performance.
- COMSOL Multiphysics is very user friendly software, easy to operate and gives good simulation results.

# References

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- A. Vivek, K.-H. Kim, G.S. Daehn, Simulation and instrumentation of electromagnetic compression of steel tubes, Journal of Materials Processing Technology 211 (2011) 840–850
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