

Voltage Induced in a Coil by a Moving Magnet

Introduction

A magnet moving axially through the center of a coil induces a voltage across the coil terminals. A practical application of this phenomenon is in shaker flashlights, where the flashlight is vigorously shaken back and forth, thereby causing a magnet to move through a multiturn coil, which provides charge to the battery. This example models the motion of a magnet through a coil and computes the induced voltages. The displacement of the magnet is significant, so the application uses a moving and sliding mesh.



Figure 1: Drawing showing a sinusoidally oscillating magnet and a multiturn coil.

Model Definition

Figure 1 illustrates the system setup, in which a magnet of strength 1.2 T is displaced sinusoidally at 4 Hz with a peak displacement of 30 mm inside of an 800 turn coil. This results in a 2D axisymmetric problem, where the modeling space is a rectangular region in the rz-plane bounded by the Magnetic Insulation boundary condition, which represents a metallic enclosure.

Both the magnet and the multiturn coils are represented by rectangles. The magnet and coil corners are not rounded off, which leads to a simpler mesh and a smaller problem size. Although the sharp corners do introduce local singularities into the magnetic fields, it is not a concern for this type of application, whose single objective is to determine the induced voltage across the coil. This voltage is computed by taking the integral of the fields

over the domains, which is quite insensitive to singularities in the fields. The corners of these domains only need to be rounded if forces and field strengths around the corners are of interest.

To define the displacement of the magnet and the surrounding air domains, the application uses the moving mesh functionality. Because neither the coil nor the air domain surrounding it needs to deform, it is sufficient to define the Moving Mesh interface in the magnet and the air domains above and below it.

When the domain movement is significant, it is warranted to use the sliding mesh functionality, introducing additional steps into the setup. When drawing the geometry, the Form Assembly functionality must be used to finalize the geometry. This feature assumes that all objects are disjoint, and automatically creates an Identity Pair at the touching boundaries between objects. The Identity Pair is used to define a Pair Continuity boundary condition in the Magnetic Fields interface, which specifies that the fields must be continuous across the noncongruent meshes. For higher accuracy, the application uses weak constraints and a smaller mesh size at these boundaries.

Solve the model in two steps. First, a stationary analysis of just the magnetic fields computes the fields due to the magnet at its starting location. This is needed to provide correct initial conditions for the subsequent transient analysis of the magnetic fields and the moving mesh. The tolerances are tightened slightly from their defaults.

Results and Discussion

Figure 2 shows the magnetic field and the mesh after 0.2 s, slightly less than the period of oscillation of the magnet, T = 0.25 s. The mesh is stretched and compressed in the air domains above and below the magnet. Although the mesh is noncongruent at the Identity Pair boundary, the Pair Continuity boundary condition ensures that the solution is continuous.

Figure 3 displays the induced voltage for the open circuit configuration of the coil.



Figure 2: Magnetic flux density and deformed mesh at the bottom of the stroke of the magnet.



Figure 3: Induced voltage in the coil over time.

4 | VOLTAGE INDUCED IN A COIL BY A MOVING MAGNET

Application Library path: ACDC_Module/Devices,_Motors_and_Generators/ induced_voltage_moving_magnet

Modeling Instructions

From the File menu, choose New.

NEW

In the New window, click 🔗 Model Wizard.

MODEL WIZARD

- I In the Model Wizard window, click 🚈 2D Axisymmetric.
- 2 In the Select Physics tree, select AC/DC > Electromagnetic Fields > Magnetic Fields (mf).
- 3 Click Add.
- 4 Click \bigcirc Study.
- 5 In the Select Study tree, select General Studies > Stationary.
- 6 Click **M** Done.

GEOMETRY I

Define the frequency of the oscillating magnet.

GLOBAL DEFINITIONS

Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- **3** In the table, enter the following settings:

Name	Expression	Value	Description
f0	4[Hz]	4 Hz	Frequency of an oscillating magnet
то	1/f0	0.25 s	Time period of an oscillating magnet
t	0[s]	0 s	Time

GEOMETRY I

I In the Model Builder window, under Component I (compl) click Geometry I.

- 2 In the Settings window for Geometry, locate the Units section.
- **3** From the **Length unit** list, choose **cm**.

Follow these instructions to construct the model geometry.

Rectangle 1 (r1)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- **3** In the **Height** text field, type **2**.
- 4 Locate the Position section. In the z text field, type -1.
- 5 Click 틤 Build Selected.

Rectangle 2 (r2)

- I In the **Geometry** toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the **Height** text field, type 8.
- **4** Locate the **Position** section. In the **r** text field, type **1.1**.
- **5** In the **z** text field, type -4.
- 6 Click 틤 Build Selected.
- 7 Click the **Zoom Extents** button in the **Graphics** toolbar.

Rectangle 3 (r3)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- **3** In the **Height** text field, type **12**.
- 4 Locate the **Position** section. In the **z** text field, type -6.
- 5 Click 📄 Build Selected.
- 6 Click the **Zoom Extents** button in the **Graphics** toolbar.

Rectangle 4 (r4)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the Width text field, type 3.
- 4 In the **Height** text field, type 12.
- 5 Locate the **Position** section. In the **r** text field, type 1.
- 6 In the z text field, type -6.

Rectangle 5 (r5)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Position section.
- **3** In the **z** text field, type **6**.

Rectangle 6 (r6)

- I In the **Geometry** toolbar, click **Rectangle**.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the Width text field, type 4.
- 4 Locate the **Position** section. In the **r** text field, type 1.
- 5 In the z text field, type 6.

Mirror I (mirI)

- I In the Geometry toolbar, click 💭 Transforms and choose Mirror.
- 2 Select the objects r5 and r6 only.
- 3 In the Settings window for Mirror, locate the Normal Vector to Line of Reflection section.
- **4** In the **r** text field, type **0**.
- **5** In the **z** text field, type 1.
- 6 Locate the Input section. Select the Keep input objects checkbox.

Rectangle 7 (r7)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- **3** In the **Height** text field, type 14.
- 4 Locate the **Position** section. In the **r** text field, type 4.
- **5** In the **z** text field, type -7.
- 6 Click 틤 Build Selected.

Form a union of **Rectangle I** and **Rectangle 3**.

Union I (uni I)

- I In the Geometry toolbar, click P Booleans and Partitions and choose Union.
- 2 Select the objects rI and r3 only.
- 3 In the Settings window for Union, click 틤 Build Selected.

Now, unify the rest of the geometry.

Union 2 (uni2)

- I In the Geometry toolbar, click 🔲 Booleans and Partitions and choose Union.
- 2 Select the objects mir1(1), mir1(2), r2, r4, r5, r6, and r7 only.
- 3 In the Settings window for Union, click 틤 Build Selected.

Finish creating the geometry by using an assembly.

Form Union (fin)

- I In the Model Builder window, under Component I (compl) > Geometry I click Form Union (fin).
- 2 In the Settings window for Form Union/Assembly, locate the Form Union/Assembly section.
- **3** From the Action list, choose Form an assembly.
- 4 Click 틤 Build Selected.
- **5** Click the **2008 Extents** button in the **Graphics** toolbar.



The final geometry is shown in the figure above.

Define boundary selections for the magnet and continuity pair.

DEFINITIONS

Magnet Boundaries

- I In the **Definitions** toolbar, click http://www.click
- 2 In the Settings window for Explicit, locate the Input Entities section.

- **3** From the **Geometric entity level** list, choose **Boundary**.
- 4 Select Boundaries 30, 31, 33, and 36 only.
- **5** In the **Label** text field, type Magnet Boundaries.



Continuity Boundaries

- I In the Definitions toolbar, click 🗞 Explicit.
- 2 In the Settings window for Explicit, locate the Input Entities section.
- **3** From the **Geometric entity level** list, choose **Boundary**.
- **4** Select Boundaries 35–37 only.



5 In the Label text field, type Continuity Boundaries.

Next, add copper for the coil and NdFeB for the magnet.

ADD MATERIAL

- I In the Materials toolbar, click 🙀 Add Material to open the Add Material window.
- 2 Go to the Add Material window.
- **3** In the tree, select **Built-in** > **Copper**.
- 4 Click the Add to Component button in the window toolbar.
- 5 In the tree, select AC/DC > Magnetic Materials (Bomatec®) > NdFeB > BMN-35.
- 6 Click the Add to Component button in the window toolbar.
- 7 In the Materials toolbar, click 🙀 Add Material to close the Add Material window.

MATERIALS

Copper (mat1)

- I In the Settings window for Material, locate the Geometric Entity Selection section.
- 2 From the Selection list, choose Manual.
- 3 Click K Clear Selection.
- 4 Select Domain 6 only.

BMN-35 (mat2)

I In the Model Builder window, click BMN-35 (mat2).

2 Select Domain 11 only.

Add the **Magnet** feature to model the moving magnet. The poles are defined on the top and bottom boundaries of the magnet.

MAGNETIC FIELDS (MF)

Magnet I

- I In the Physics toolbar, click **Domains** and choose Magnet.
- **2** Select Domain 11 only.

North I

- I In the Model Builder window, click North I.
- 2 Select Boundary 33 only.

South I

- I In the Model Builder window, click South I.
- 2 Select Boundary 31 only.

Next, add the Coil feature to model the pickup multiturn coil.

Coil I

- I In the Physics toolbar, click **Domains** and choose **Coil**.
- **2** Select Domain 6 only.
- 3 In the Settings window for Coil, locate the Material Type section.
- 4 From the Material type list, choose Solid.
- 5 Locate the Coil section. From the Conductor model list, choose Homogenized multiturn.
- 6 Locate the Homogenized Conductor section. In the *N* text field, type 800.
- 7 From the list, choose User defined.
- 8 Find the **High-frequency effective loss** subsection. Clear the **Include harmonic loss** checkbox.
- **9** In the *a* text field, type $pi*(0.5[mm])^2$.





II Click the 🐱 Show More Options button in the Model Builder toolbar.

12 In the Show More Options dialog, in the tree, select the checkbox for the node Physics > Advanced Physics Options.

I3 Click OK.

Add a continuity boundary condition and enable the weak constraints features.

Continuity I

In the Physics toolbar, click Pairs and choose Continuity.

Magnetic Insulation 1

- I In the Model Builder window, click Magnetic Insulation I.
- **2** In the **Settings** window for **Magnetic Insulation**, click to expand the **Constraint Settings** section.
- 3 From the Constraint list, choose Weak constraints.

Continuity I

- I In the Model Builder window, click Continuity I.
- 2 In the Settings window for Continuity, locate the Pair Selection section.
- 3 Click + Add.
- 4 In the Add dialog, select Identity Boundary Pair I (apl) in the Pairs list.

- 5 Click OK.
- 6 In the Settings window for Continuity, click to expand the Constraint Settings section.
- 7 From the Constraint list, choose Weak constraints.

Define the Moving Mesh only in the domains to the left of the continuity pair.

COMPONENT I (COMPI)

Prescribed Deformation 1

- I In the Model Builder window, expand the Continuity I node.
- 2 Right-click Component I (compl) and choose Moving Mesh > Prescribed Deformation.
- **3** Select Domain 11 only.
- **4** In the **Settings** window for **Prescribed Deformation**, locate the **Prescribed Deformation** section.



5 Specify the *dx* vector as



Prescribed Deformation 2

I In the Moving Mesh toolbar, click / Prescribed Deformation.

2 Select Domain 12 only.

- **3** In the **Settings** window for **Prescribed Deformation**, locate the **Prescribed Deformation** section.
- **4** Specify the *dx* vector as

0	R
30[mm]*sin(2*pi*f0*t)*(6[cm]-Z)/5[cm]	

Prescribed Deformation 3

- I In the Moving Mesh toolbar, click / Prescribed Deformation.
- **2** Select Domain 10 only.
- **3** In the **Settings** window for **Prescribed Deformation**, locate the **Prescribed Deformation** section.



Ζ

Define the Infinite Element Domain.

30[mm]*sin(2*pi*f0*t)*(6[cm]+Z)/5[cm]

DEFINITIONS

Infinite Element Domain I (ie I) I In the Definitions toolbar, click $i \sim$ Infinite Element Domain.

- 2 In the Settings window for Infinite Element Domain, locate the Geometry section.
- **3** From the **Type** list, choose **Cylindrical**.
- 4 Select Domains 1–3, 5, and 7–9 only.

MESH I

- I In the Model Builder window, under Component I (compl) click Mesh I.
- 2 In the Settings window for Mesh, locate the Physics-Controlled Mesh section.
- 3 From the Element size list, choose Fine.

Size 1

- I Right-click Component I (compl) > Mesh I and choose Size.
- 2 In the Settings window for Size, locate the Geometric Entity Selection section.
- 3 From the Geometric entity level list, choose Boundary.
- 4 Select Boundaries 28, 29, and 31-37 only.
- 5 Locate the Element Size section. Click the Custom button.
- 6 Locate the Element Size Parameters section.
- 7 Select the Maximum element size checkbox. In the associated text field, type 4[mm].

Size 2

- I In the Model Builder window, right-click Mesh I and choose Size.
- 2 In the Settings window for Size, locate the Geometric Entity Selection section.
- 3 From the Geometric entity level list, choose Boundary.
- 4 Select Boundary 9 only.
- 5 Locate the Element Size section. Click the Custom button.
- 6 Locate the Element Size Parameters section.
- 7 Select the Maximum element size checkbox. In the associated text field, type 1 [mm].

Edge 1

- I In the Mesh toolbar, click \bigwedge More Generators and choose Edge.
- 2 Select Boundaries 28, 31–35, and 37 only.

Mapped I

- I In the Mesh toolbar, click Mapped.
- 2 In the Settings window for Mapped, locate the Domain Selection section.
- 3 From the Geometric entity level list, choose Domain.
- 4 Select Domains 10 and 12 only.

Free Triangular 1

- I In the Mesh toolbar, click K Free Triangular.
- 2 In the Settings window for Free Triangular, locate the Domain Selection section.
- 3 From the Geometric entity level list, choose Domain.
- **4** Select Domains 4, 6, and 11 only.

Copy Edge 1

- I Right-click Mesh I and choose Copying Operations > Copy Edge.
- 2 Select Boundaries 12 and 34 only.
- 3 In the Settings window for Copy Edge, locate the Destination Boundaries section.
- **4** Click to select the **I** Activate Selection toggle button.
- **5** Select Boundaries 6 and 13 only.

Copy Edge 2

- I Right-click Mesh I and choose Copying Operations > Copy Edge.
- **2** Select Boundaries 10 and 29 only.
- 3 In the Settings window for Copy Edge, locate the Destination Boundaries section.
- **4** Click to select the **EXACTIVATE Selection** toggle button.
- **5** Select Boundaries 2 and 8 only.

Edge 2

- I In the Mesh toolbar, click \bigwedge More Generators and choose Edge.
- 2 Select Boundaries 1, 4, 18, 19, 21–25, and 27 only.

Distribution I

Right-click Edge 2 and choose Distribution.

Copy Edge 3

- I In the Model Builder window, right-click Mesh I and choose Copying Operations > Copy Edge.
- 2 In the Settings window for Copy Edge, locate the Source Boundaries section.
- **3** Click Remove from Selection.
- **4** Select Boundaries 1 and 4 only.
- **5** Locate the **Destination Boundaries** section. Click to select the **Destination Boundaries** section.
- 6 Select Boundaries 7 and 11 only.

Mapped 2

- I In the Mesh toolbar, click Mapped.
- 2 In the Settings window for Mapped, click 📗 Build All.

The mesh should look like that shown in the figure below.



Now, add the **Time Dependent** study step and solve the problem in the time domain. The **Time Dependent** study automatically takes the initial values for the vector potential from the stationary solution. Some tuning of the solver is done in order to speedup the calculation.

STUDY I

Step 2: Time Dependent

- I In the Study toolbar, click Study Steps and choose Time Dependent > Time Dependent.
- 2 In the Settings window for Time Dependent, locate the Study Settings section.
- 3 In the **Output times** text field, type range(0,T0/100,T0).

Use the following steps to improve convergence speed and robustness.

Solution 1 (soll)

In the Study toolbar, click **Show Default Solver**.

Step 1: Stationary

I In the Model Builder window, under Study I click Step I: Stationary.

- 2 In the Settings window for Stationary, locate the Study Settings section.
- **3** From the **Tolerance** list, choose **User controlled**.
- 4 In the **Relative tolerance** text field, type 1e-4.

Solution 1 (soll)

- I In the Model Builder window, expand the Solution I (soll) node.
- 2 In the Model Builder window, expand the Study I > Solver Configurations > Solution I (soll) > Time-Dependent Solver I node, then click Fully Coupled I.
- **3** In the **Settings** window for **Fully Coupled**, click to expand the **Method and Termination** section.
- **4** From the **Jacobian update** list, choose **On every iteration**.
- **5** In the **Study** toolbar, click **= Compute**.

RESULTS

Magnetic Flux Density (mf)

Use the following steps to generate a plot of the magnetic flux density norm and deformed mesh as shown in Figure 2.

- I In the Settings window for 2D Plot Group, locate the Data section.
- 2 From the Time (s) list, choose 0.2.
- 3 In the Model Builder window, expand the Magnetic Flux Density (mf) node.

Contour I, Streamline I

- I In the Model Builder window, under Results > Magnetic Flux Density (mf), Ctrl-click to select Streamline I and Contour I.
- 2 Right-click and choose Disable.

Mesh I

- I In the Model Builder window, right-click Magnetic Flux Density (mf) and choose Mesh.
- 2 In the Settings window for Mesh, locate the Coloring and Style section.
- **3** From the **Element color** list, choose **None**.
- 4 In the Magnetic Flux Density (mf) toolbar, click 💿 Plot.

Finally, reproduce the plot for an induced voltage in the coil.

ID Plot Group 4

In the **Results** toolbar, click \sim **ID Plot Group**.

Global I

- I Right-click ID Plot Group 4 and choose Global.
- 2 In the Settings window for Global, click Replace Expression in the upper-right corner of the y-Axis Data section. From the menu, choose Component I (compl) > Magnetic Fields > Coil parameters > mf.VCoil_I Coil voltage V.
- 3 In the ID Plot Group 4 toolbar, click 💿 Plot.

Coil Induced Voltage

- I In the Model Builder window, right-click ID Plot Group 4 and choose Rename.
- 2 In the Rename ID Plot Group dialog, type Coil Induced Voltage in the New label text field.
- 3 Click OK.

Compare the plot with Figure 3.

 $20 \ \mid \ \mbox{voltage induced in a coil by a moving magnet}$