

Optimal Design for the Grating Coupler of Surface Plasmons

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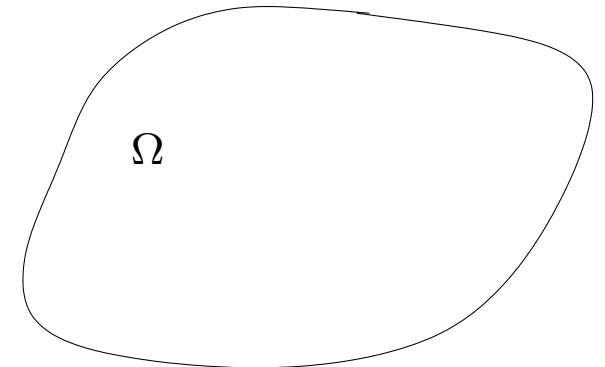
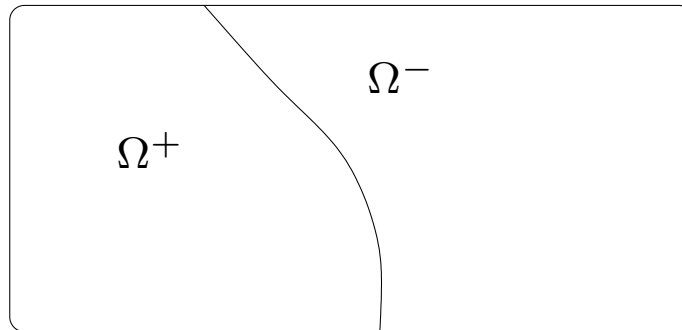
Outline

- General formulation of the shape optimization
- Background of Plasmon Wave
- Shape gradient of the grating coupler
- Numerical Results

General Problem Formulation

$$\begin{aligned} \min_{\Omega \in \mathcal{A}_{ad}} J(\Omega) &= j(\Phi(\Omega)) \\ A(\Phi(\Omega)) &= F \end{aligned}$$

where A is a differential operator.



Adjoint Variable(Lagrange Multiplier)

$$L(\Phi, \Psi) = j(\Phi) - \int_{\Omega} (A(\Phi) - F)\Psi dx$$

Taking the variable w.r.t Φ , we can get the equation for Ψ

$$\delta_{\Phi} L = 0$$

or

$$A^*(\Psi) = \partial_{\Phi} j(\Phi)$$

Dynamic Shape Optimization(1)

Let Ω evolves with time, i.e

$$\frac{d}{dt}x = \mathbf{u}(x, t), \quad x \in \Omega_t$$

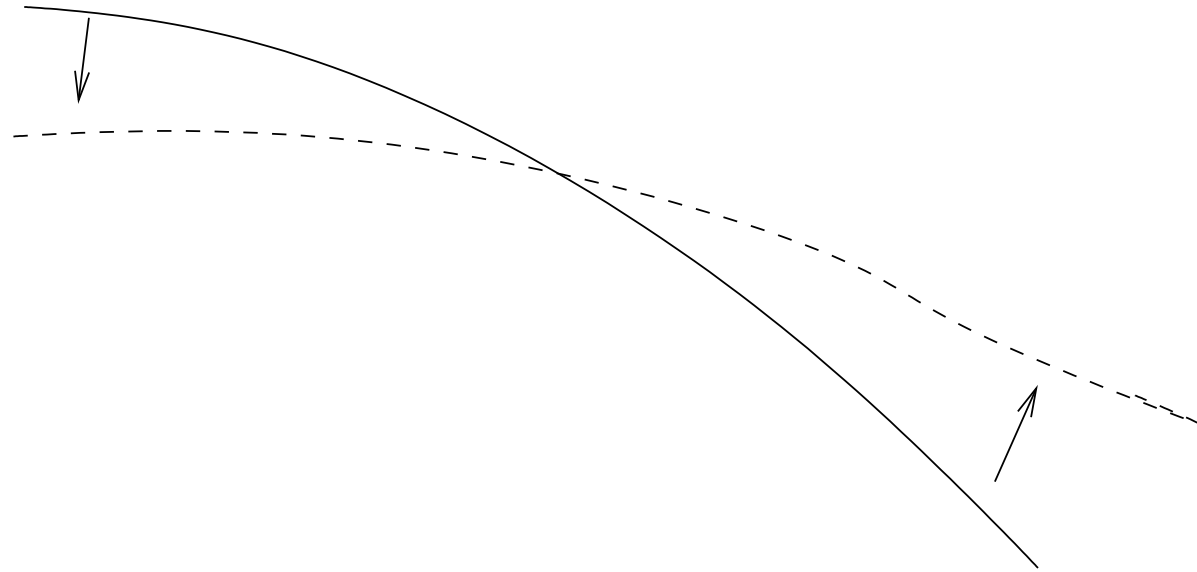
Then

$$\begin{aligned} \frac{d}{dt}j(\Phi) &= \left\langle \partial_{\Phi}j(\Phi), \frac{d}{dt}\Phi \right\rangle \\ &= \left\langle A^*(\Psi), \frac{d}{dt}\Phi \right\rangle \end{aligned}$$

Dynamic Shape Optimization(2)

$$\begin{aligned}\frac{d}{dt}j(\Phi) &= \langle \partial_{\Phi}j(\Phi), \frac{d}{dt}\Phi \rangle \\ &= \langle A^*(\Psi), \frac{d}{dt}\Phi \rangle \\ &= \langle \Psi, A \frac{d}{dt}\Phi \rangle \\ &= \langle \Psi, \frac{d}{dt}(A\Phi) \rangle - \langle \Psi, (\frac{d}{dt}A)\Phi \rangle \\ &= -\langle \Psi, (\frac{d}{dt}A)\Phi \rangle\end{aligned}$$

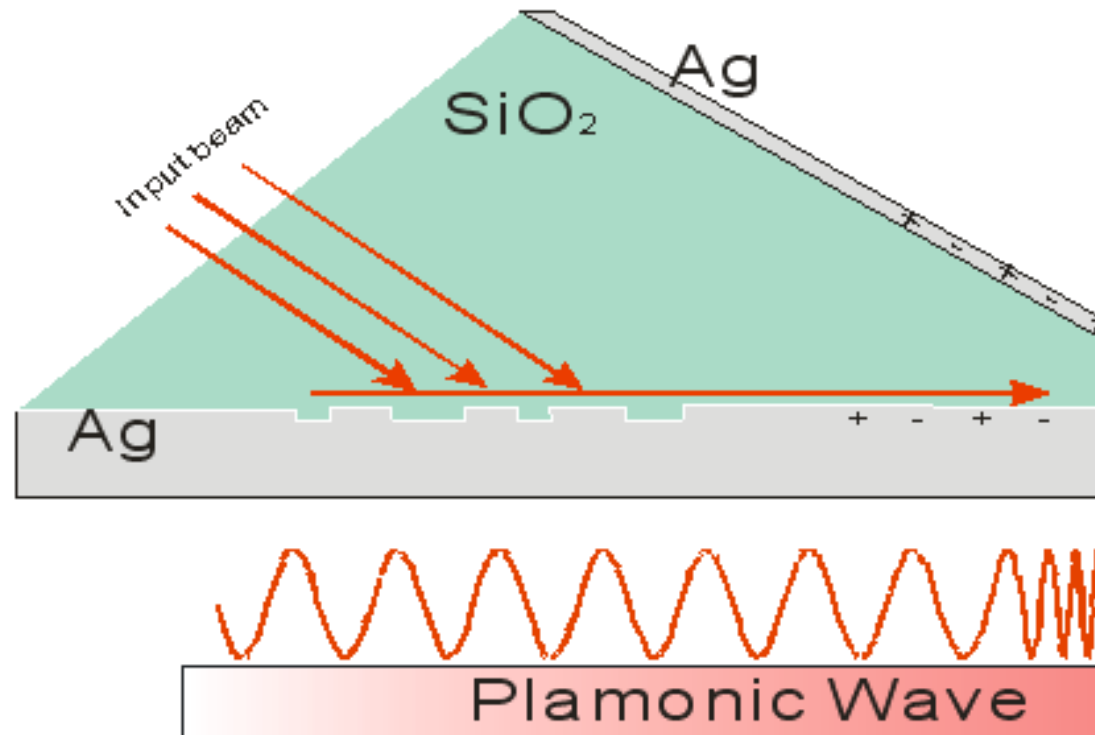
Dynamic Shape Optimization(3)



Usually,

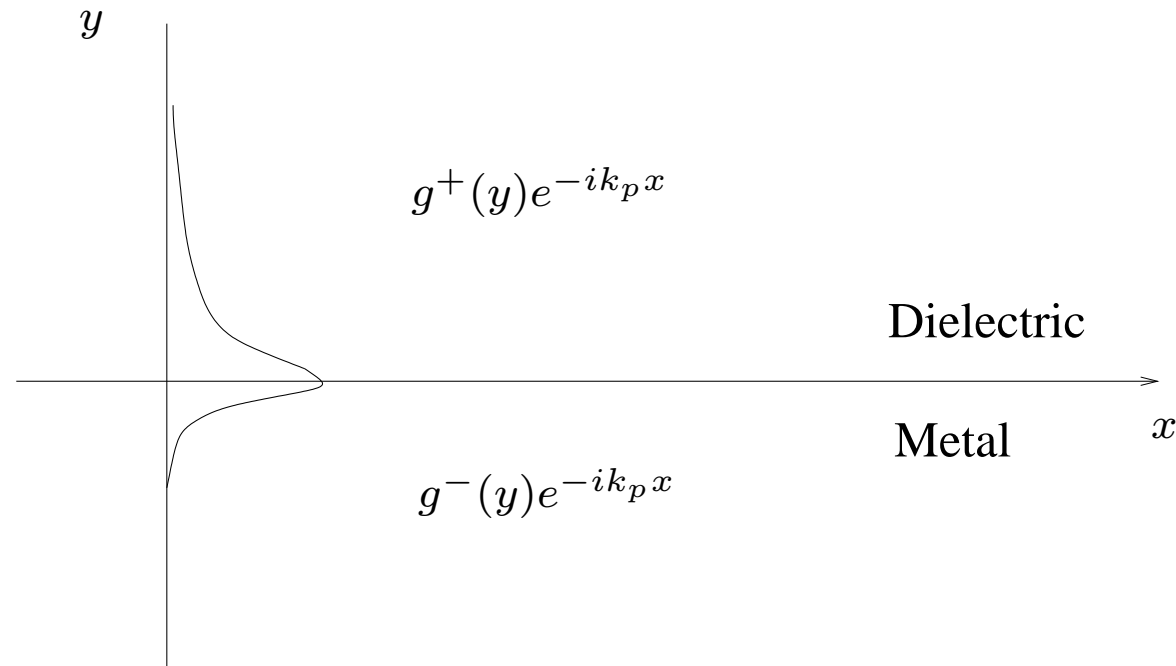
$$\frac{d}{dt}j(\Phi) = \int_{\Gamma_m} f(\Phi, \Psi) \mathbf{u} \cdot \mathbf{n} dS$$

Physical Background of Plasmon Wave



Physical Background of Plasmon Wave

A Wave travelling along the interface between metal and dielectrics.



Physical Background of Plasmon Wave

The dispersion relation is given by

$$k_p = \sqrt{\frac{\epsilon_m(\omega)\epsilon_d(\omega)}{\epsilon_m(\omega) + \epsilon_d(\omega)}}$$

For existence of plasmon wave

$$\epsilon_m(\omega) < -\epsilon_d(\omega)$$

Physical Background of Plasmon Wave

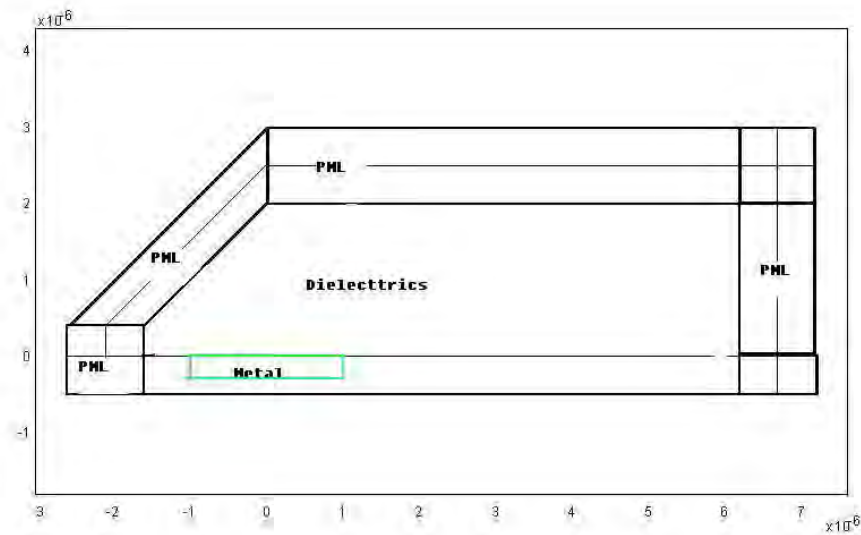
$$\begin{aligned}\nabla \times \mathbf{H} &= \frac{\partial(\epsilon\mathbf{E})}{\partial t} \\ \nabla \times \mathbf{E} &= -\frac{\partial(\mu\mathbf{H})}{\partial t}\end{aligned}$$

Time Harmonic, Transverse Magnetic

$$\mathbf{E} = \begin{pmatrix} E_x(x, y) \\ E_y(x, y) \\ 0 \end{pmatrix} e^{j\omega t}, \quad \mathbf{H} = \begin{pmatrix} 0 \\ 0 \\ H_z(x, y) \end{pmatrix} e^{j\omega t}$$

Physical Background of Plasmon Wave

$$\nabla \cdot \epsilon_r^{-1} \nabla H_z + k_0^2 H_z = 0, \quad k_0^2 = \omega^2 \epsilon_0 \mu_0$$



Problem Formulation

$$\min J = \frac{1}{2} \int_{\Gamma} \operatorname{Re}(\vec{E} \times \vec{H}^*) \cdot \mathbf{n} ds$$

Using the relation

$$\begin{aligned} \vec{E} = \frac{1}{j\omega\epsilon} \nabla \times \vec{H} &= \frac{1}{j\omega\epsilon} \left(\frac{\partial H_z}{\partial y}, -\frac{\partial H_z}{\partial x}, 0 \right) \\ \operatorname{Re}(\vec{E} \times \vec{H}) \cdot \mathbf{n} &= \operatorname{Re} \left(\frac{1}{j\omega\epsilon} \left(-\frac{\partial H_z}{\partial x} H_z^*, \frac{\partial H_z}{\partial y} H_z^*, 0 \right) \right) \cdot (1, 0, 0) \\ &= \operatorname{Re} \left(\frac{j}{\omega\epsilon} \frac{\partial H_z}{\partial x} H_z^* \right) \\ \frac{\partial H_z}{\partial x} &= -jk_p H_z \end{aligned}$$

Problem Formulation

$$\operatorname{Re}(\vec{E} \times \vec{H}^*) \cdot \mathbf{n} = \frac{1}{\omega \operatorname{Re}(\epsilon)} |Hz|^2$$

$$\begin{aligned} \min \quad & J = \frac{1}{2} \int_{\Gamma} \frac{1}{\operatorname{Re}(\epsilon)} |Hz|^2 dx \\ & \nabla \cdot \epsilon_r^{-1} \nabla H_z + k_0^2 H_z = 0 \\ & \nabla \cdot \epsilon_r^{-1} \nabla \tilde{H}_z + k_0^2 \tilde{H}_z = \frac{1}{\operatorname{Re}(\epsilon_r)} Hz^* \delta_{\Gamma} \end{aligned}$$

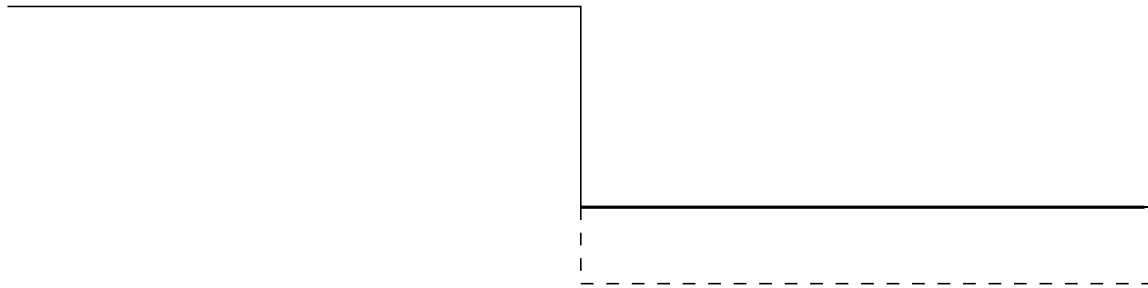
Gradient of the Objective Functional w.r.t time

$$\begin{aligned}\frac{d}{dt}J &= \operatorname{Re} \left(\int_{\gamma} \left[\frac{1}{\epsilon_r} \left(2 \frac{\partial H z}{\partial n} \frac{\partial \tilde{H} z}{\partial n} - \nabla H z \cdot \nabla \tilde{H} z \right) \right] ds \right) \\ &= \operatorname{Re} \left(\left(\frac{1}{\epsilon_r^+} - \frac{1}{\epsilon_r^-} \right) \int_{\gamma} \nabla H z^+ \cdot \nabla \tilde{H} z^- \mathbf{u} \cdot \mathbf{n} ds \right) \\ &= \operatorname{Re} \left(\left(\frac{1}{\epsilon_r^+} - \frac{1}{\epsilon_r^-} \right) \int_{\gamma} \nabla H z^- \cdot \nabla \tilde{H} z^+ \mathbf{u} \cdot \mathbf{n} ds \right)\end{aligned}$$

Gradient of the Objective Functional w.r.t position

For finite number of gratings,

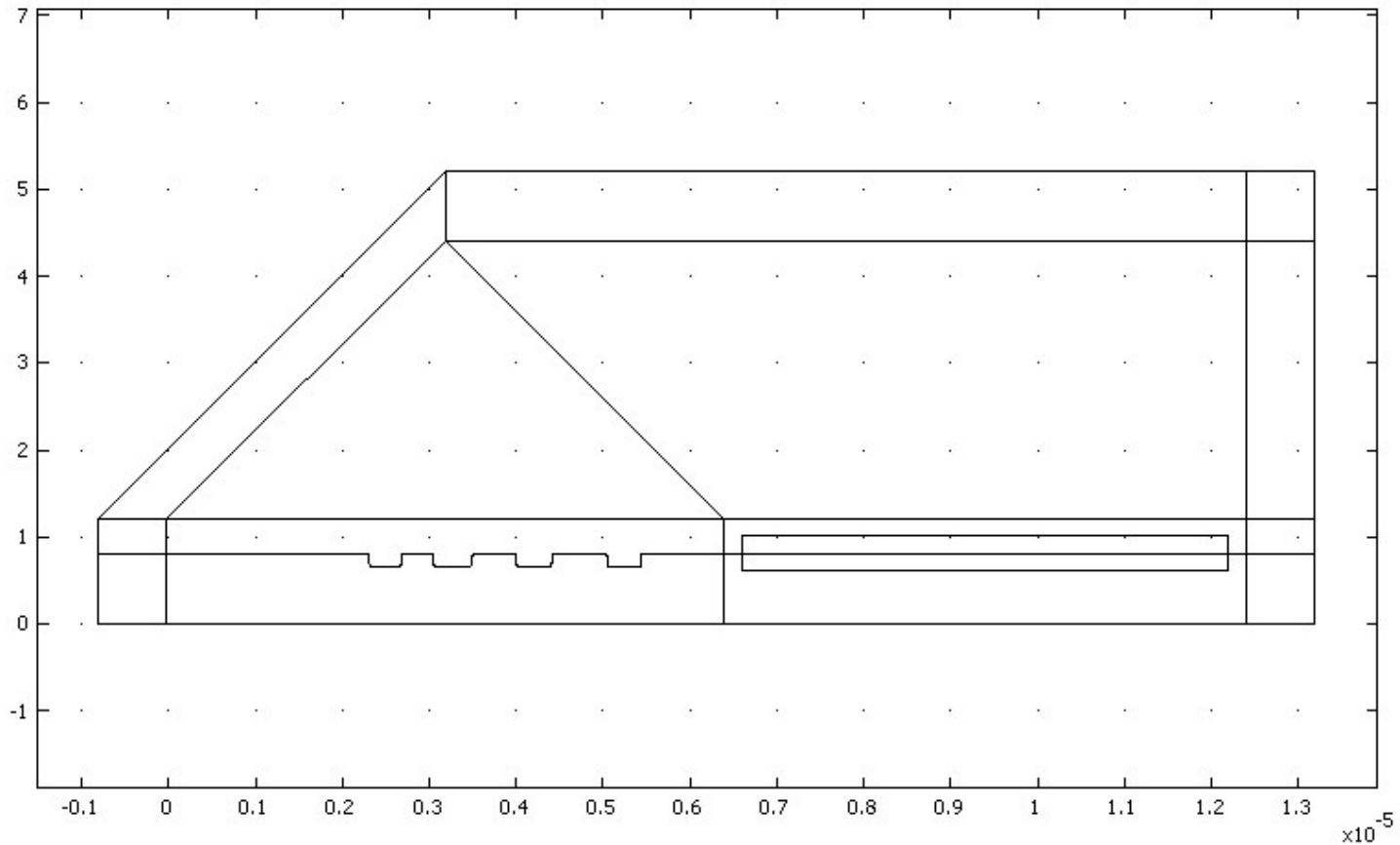
$$J = J(x_1, x_2, \dots, x_N, h),$$



$$\frac{dJ}{dt} = \frac{\partial J}{\partial h} v_h = \int_{\gamma_h} \nabla H z^- \cdot \nabla \tilde{H} z^+ v_h ds$$

$$\frac{\partial J}{\partial h} = \int_{\gamma_h} \nabla H z^- \cdot \nabla \tilde{H} z^+ ds$$

Geometry



Numerical algorithm

During each iteration

0. Solve $\nabla \cdot \frac{1}{\epsilon} \nabla H_z + k_0^2 H_z = 0$

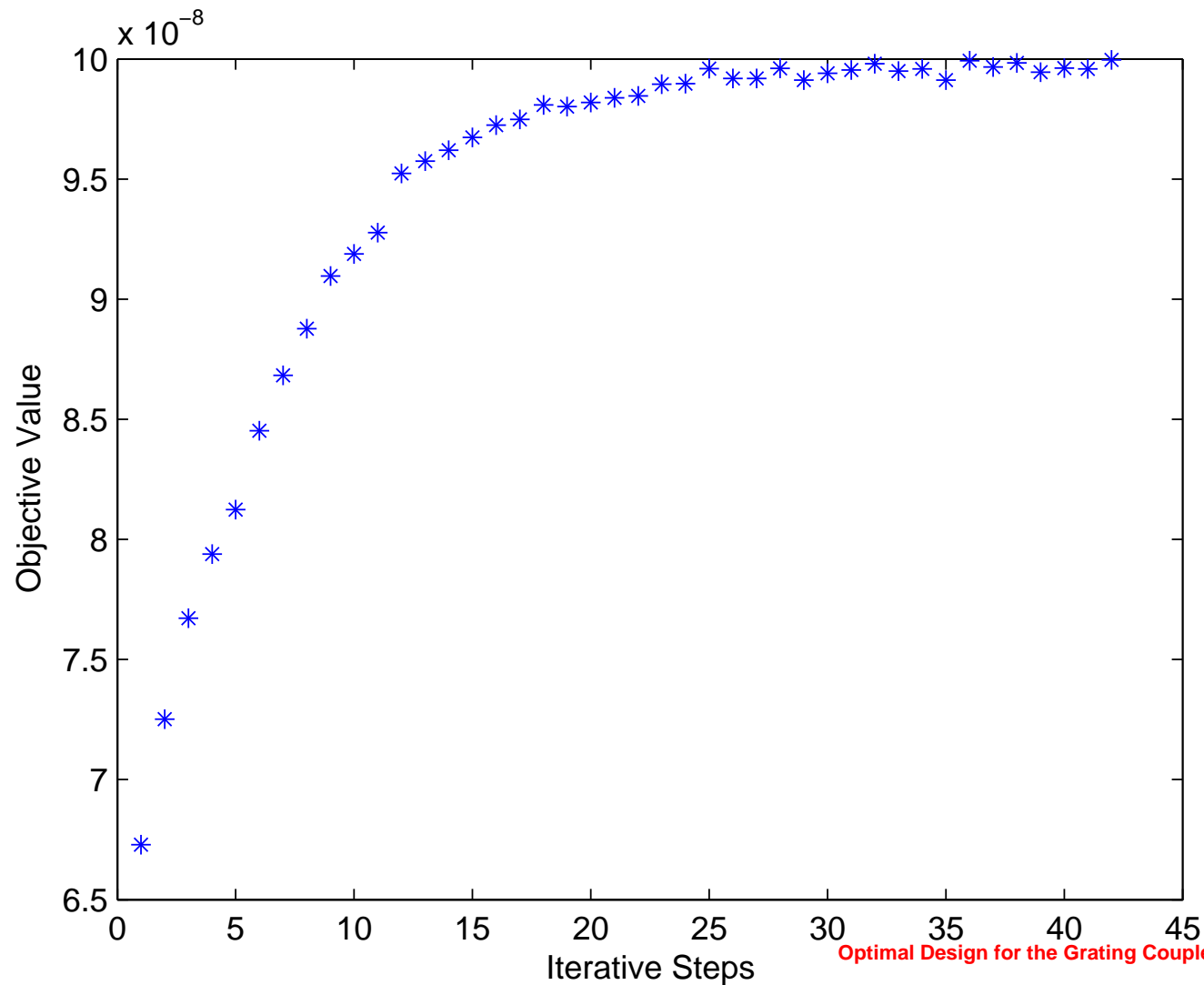
0. Solve for the adjoint variable

$$\nabla \cdot \epsilon_r^{-1} \nabla \tilde{H}_z + k_0^2 \tilde{H}_z = \frac{1}{\text{Re}(\epsilon_r)} H_z^* \delta_\Gamma$$

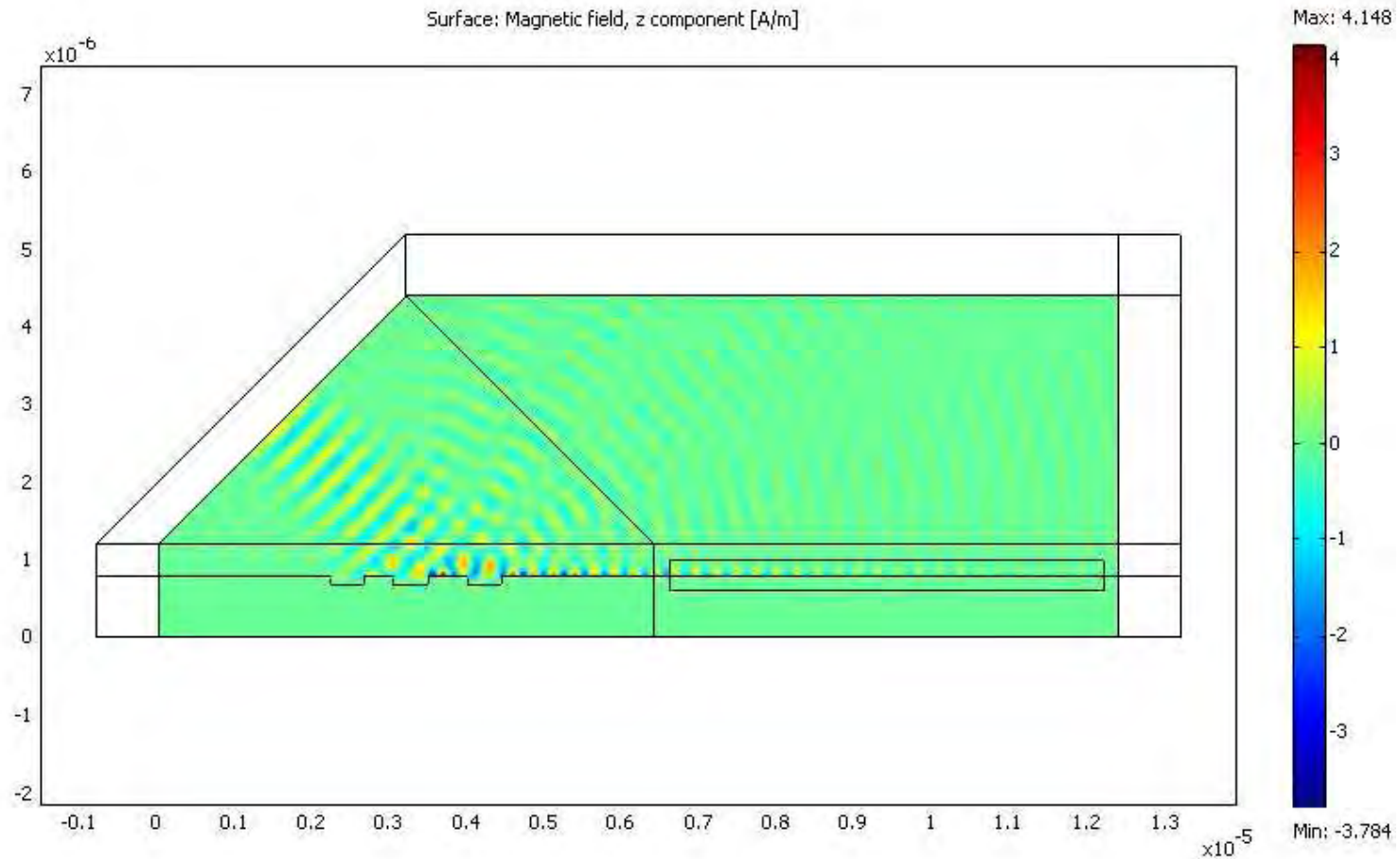
0. Calculate the partial derivatives $\frac{\partial J}{\partial x_i}, \frac{\partial J}{\partial h}$

0. Gradient ascent to update the geometry

Numerical Result



Numerical Result





The End!